

Periodic waves in discrete MKDV equation: modulational instability and rogue waves

Dmitry E. Pelinovsky

Department of Mathematics, McMaster University, Canada

<http://dmpeli.math.mcmaster.ca>

The rogue wave of the cubic NLS equation

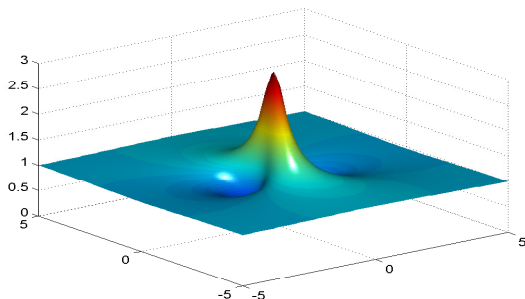
The focusing nonlinear Schrödinger (NLS) equation

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

admits the exact solution

$$\psi(x, t) = \left[1 - \frac{4(1 + 2it)}{1 + 4x^2 + 4t^2} \right] e^{it}.$$

It was discovered by H. Peregrine (1983) and was labeled as *the rogue wave*.



Traveling periodic waves

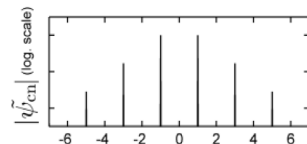
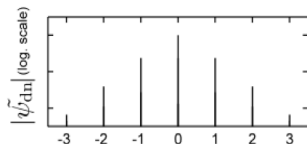
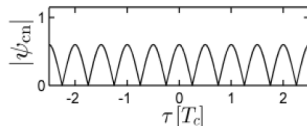
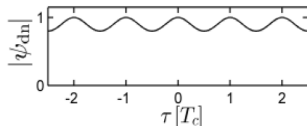
The focusing nonlinear Schrödinger (NLS) equation

$$i\psi_t + \frac{1}{2}\psi_{xx} + |\psi|^2\psi = 0$$

admits the periodic traveling and standing wave solutions, e.g. the dnoidal and cnoidal waves:

$$\psi_{\text{dn}}(x, t) = \text{dn}(x; k) e^{i(1-k^2/2)t}, \quad \psi_{\text{cn}}(x, t) = \text{cn}(x; k) e^{i(k^2-1/2)t},$$

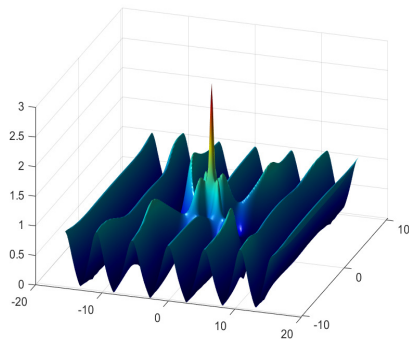
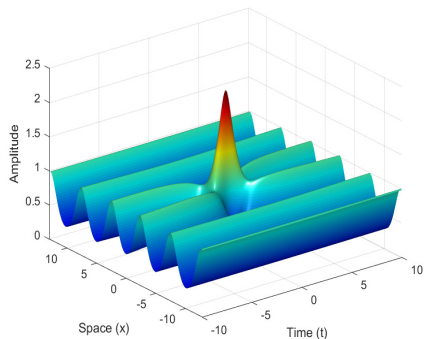
where $k \in (0, 1)$ is elliptic modulus.



Rogue wave on background of periodic waves

J. Chen, D. Pelinovsky, Proceedings A **474** (2018) 20170814

J. Chen, D. Pelinovsky, R. White, Physica D **405** (2020) 132378



Other examples of integrable Hamiltonian systems

- Modified Korteweg–de Vries equation

$$u_t + 6u^2 u_x + u_{xxx} = 0$$

Dnoidal periodic waves are modulationally stable.

Cnoidal periodic waves are modulationally unstable.

J. Chen & D. Pelinovsky, *Nonlinearity* **31** (2018) 1955–1980

- Sine–Gordon equation

$$u_{tt} - u_{xx} + \sin(u) = 0$$

Same conclusion.

D. Pelinovsky & R. White, *Proceedings A* **476** (2020) 20200490

- Derivative NLS equation

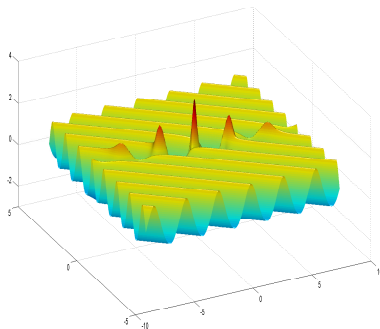
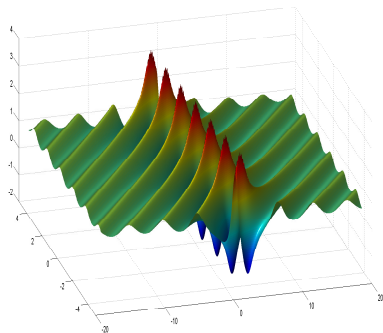
$$i\psi_t + \psi_{xx} + i(|\psi|^2\psi)_x = 0.$$

There exist modulationally stable periodic waves.

J. Chen, D. Pelinovsky, & J. Upsal, *J. Nonlinear Science* **31** (2021) 58

Rogue wave for the modified KdV equation

J. Chen & D. Pelinovsky, *Journal of Nonlinear Science* **29** (2019) 2797–2843



Discrete modified KdV equation

It is considered to be the third-order flow in the Ablowitz–Ladik hierarchy:

$$\dot{u}_n = (1 + u_n^2)(u_{n+1} - u_{n-1}), \quad n \in \mathbb{Z},$$

where $u_n = u_n(t)$ is real.

In the continuum limit, long waves of small amplitudes can be modeled by

$$u_n(t) = \varepsilon u(\varepsilon(n + 2t), \frac{1}{3}\varepsilon^3 t),$$

satisfy the continuous the mKdV equation

$$u_\tau = 6u^2 u_\xi + u_{\xi\xi\xi},$$

where $u = u(\xi, \tau)$ with $\xi := \varepsilon(n + 2t)$ and $\tau := \frac{1}{3}\varepsilon^3 t$, and ε is small parameter.

Lax equations

DMKDV is a compatibility condition of the linear Lax system

$$\varphi_{n+1} = \frac{1}{\sqrt{1+u_n^2}} \begin{pmatrix} \lambda & u_n \\ -u_n & \lambda^{-1} \end{pmatrix} \varphi_n$$

and

$$\dot{\varphi}_n = \begin{pmatrix} \frac{1}{2}(\lambda^2 - \lambda^{-2}) & \lambda u_n + \lambda^{-1} u_{n-1} \\ -\lambda u_{n-1} - \lambda^{-1} u_n & -\frac{1}{2}(\lambda^2 - \lambda^{-2}) \end{pmatrix} \varphi_n.$$

There exists another Lax system representation:

$$\varphi_{n+1} = \begin{pmatrix} \lambda & u_n \\ -u_n & \lambda^{-1} \end{pmatrix} \varphi_n$$

and

$$\dot{\varphi}_n = \begin{pmatrix} \frac{1}{2}(\lambda^2 - \lambda^{-2}) + u_n u_{n-1} & \lambda u_n + \lambda^{-1} u_{n-1} \\ -\lambda u_{n-1} - \lambda^{-1} u_n & -\frac{1}{2}(\lambda^2 - \lambda^{-2}) + u_n u_{n-1} \end{pmatrix} \varphi_n.$$

Nonlinearization method

If $\varphi_n = (p_n, q_n)^T$ is a solution of Lax system for $\lambda = \lambda_1$,
 then $\varphi_n = (-q_n, p_n)^T$ is a solution for $\lambda = \lambda_1^{-1}$.

Assume the relation between solutions of the DMKV and Lax systems:

$$u_n = \lambda_1 p_n^2 + \lambda_1^{-1} q_n^2, \quad n \in \mathbb{Z}.$$

Then, $\varphi_n = (p_n, q_n)^T$ satisfies the nonlinear symplectic map

$$\begin{pmatrix} p_{n+1} \\ q_{n+1} \end{pmatrix} = \frac{1}{\sqrt{1 + (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2)^2}} \begin{pmatrix} \lambda_1 p_n + (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2) q_n \\ \lambda_1^{-1} q_n - (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2) p_n \end{pmatrix}$$

and the nonlinear Hamiltonian system

$$\frac{dp_n}{dt} = \frac{\partial H}{\partial q_n}, \quad \frac{dq_n}{dt} = -\frac{\partial H}{\partial p_n},$$

with

$$H(p_n, q_n) = \frac{1}{2}(\lambda_1^2 - \lambda_1^{-2})p_n q_n + \frac{1}{2}(\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2)(\lambda_1^{-1} p_n^2 + \lambda_1 q_n^2).$$

Nonlinearization method

If $\varphi_n = (p_n, q_n)^T$ is a solution of Lax system for $\lambda = \lambda_1$,
 then $\varphi_n = (-q_n, p_n)^T$ is a solution for $\lambda = \lambda_1^{-1}$.

Assume the relation between solutions of the DMKV and Lax systems:

$$u_n = \lambda_1 p_n^2 + \lambda_1^{-1} q_n^2, \quad n \in \mathbb{Z}.$$

Then, $\varphi_n = (p_n, q_n)^T$ satisfies the nonlinear symplectic map

$$\begin{pmatrix} p_{n+1} \\ q_{n+1} \end{pmatrix} = \frac{1}{\sqrt{1 + (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2)^2}} \begin{pmatrix} \lambda_1 p_n + (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2) q_n \\ \lambda_1^{-1} q_n - (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2) p_n \end{pmatrix}$$

and the nonlinear Hamiltonian system

$$\frac{dp_n}{dt} = \frac{\partial H}{\partial q_n}, \quad \frac{dq_n}{dt} = -\frac{\partial H}{\partial p_n},$$

with

$$H(p_n, q_n) = \frac{1}{2}(\lambda_1^2 - \lambda_1^{-2})p_n q_n + \frac{1}{2}(\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2)(\lambda_1^{-1} p_n^2 + \lambda_1 q_n^2).$$

Restrictions on the class of admissible solutions

In addition to

$$u_n = \lambda_1 p_n^2 + \lambda_1^{-1} q_n^2, \quad n \in \mathbb{Z},$$

one can easily prove the relation

$$u_{n-1} = \lambda_1^{-1} p_n^2 + \lambda_1 q_n^2, \quad n \in \mathbb{Z}.$$

Since $F_1 = 2H(p_n, q_n) = (\lambda_1^2 - \lambda_1^{-2})p_n q_n + (\lambda_1 p_n^2 + \lambda_1^{-1} q_n^2)(\lambda_1^{-1} p_n^2 + \lambda_1 q_n^2)$ is independent of $n \in \mathbb{Z}$ and $t \in \mathbb{R}$, we obtain

$$p_n^2 = \frac{\lambda_1 u_n - \lambda_1^{-1} u_{n-1}}{\lambda_1^2 - \lambda_1^{-2}}, \quad q_n^2 = \frac{\lambda_1 u_{n-1} - \lambda_1^{-1} u_n}{\lambda_1^2 - \lambda_1^{-2}}, \quad p_n q_n = \frac{F_1 - u_n u_{n-1}}{\lambda_1^2 - \lambda_1^{-2}}.$$

One can show that u_n satisfies the stationary discrete equation

$$(1 + u_n^2)(u_{n+1} + u_{n-1}) = \omega u_n, \quad n \in \mathbb{Z},$$

where $\omega := \lambda_1^2 + \lambda_1^{-2} + 2F_1$. **Connection to traveling solutions of DMKDV?!**

Integrability of the nonlinear Hamiltonian system

The Hamiltonian system for (p_n, q_n) is obtained from the Lax equations

$$W(p_{n+1}, q_{n+1}, \lambda)U(u_n, \lambda_1) - U(u_n, \lambda_1)W(p_n, q_n, \lambda) = 0$$

and

$$\frac{d}{dt}W(p_n, q_n, \lambda) = V(u_n, \lambda_1)W(p_n, q_n, \lambda) - W(p_n, q_n, \lambda)V(u_n, \lambda_1),$$

where

$$W(p_n, q_n, \lambda) = \begin{pmatrix} \frac{1}{2} - \frac{\lambda_1^2 p_n q_n}{\lambda^2 - \lambda_1^2} + \frac{\lambda_1^{-2} p_n q_n}{\lambda^2 - \lambda_1^{-2}} & \lambda \left(\frac{\lambda_1 p_n^2}{\lambda^2 - \lambda_1^2} + \frac{\lambda_1^{-1} q_n^2}{\lambda^2 - \lambda_1^{-2}} \right) \\ -\lambda \left(\frac{\lambda_1 q_n^2}{\lambda^2 - \lambda_1^2} + \frac{\lambda_1^{-1} p_n^2}{\lambda^2 - \lambda_1^{-2}} \right) & -\frac{1}{2} + \frac{\lambda_1^2 p_n q_n}{\lambda^2 - \lambda_1^2} - \frac{\lambda_1^{-2} p_n q_n}{\lambda^2 - \lambda_1^{-2}} \end{pmatrix}$$

satisfies

$$\det W(p_n, q_n, \lambda) = -\frac{1}{4} + \frac{\lambda^2 F_1}{(\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})}.$$

Algebraic polynomial for the traveling periodic waves

Due to the squared eigenfunction constraints, we also have

$$W(p_n, q_n, \lambda) = \begin{pmatrix} \frac{1}{2} - \frac{\lambda^2(F_1 - u_n u_{n-1})}{(\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})} & \frac{\lambda(\lambda^2 u_n - u_{n-1})}{(\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})} \\ -\frac{\lambda(\lambda^2 u_{n-1} - u_n)}{(\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})} & -\frac{1}{2} + \frac{\lambda^2(F_1 - u_n u_{n-1})}{(\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})} \end{pmatrix},$$

which gives

$$\det W(p_n, q_n, \lambda) = -\frac{P(\lambda)}{4(\lambda^2 - \lambda_1^2)^2(\lambda^2 - \lambda_1^{-2})^2},$$

where

$$P(\lambda) := \lambda^8 - 2\omega\lambda^6 + (2 + \omega^2 - 4F_1^2)\lambda^4 - 2\omega\lambda^2 + 1.$$

Thus, λ_1 is selected from two quadruplets of $P(\lambda)$:

$$P(\lambda) = (\lambda^2 - \lambda_1^2)(\lambda^2 - \lambda_1^{-2})(\lambda^2 - \lambda_2^2)(\lambda^2 - \lambda_2^{-2}).$$

Dnoidal periodic waves

These are solutions of the form

$$u_n(t) = \frac{\operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)} \operatorname{dn}(\alpha n + ct; k), \quad c = \frac{2\operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)}, \quad \omega = \frac{2\operatorname{dn}(\alpha; k)}{\operatorname{cn}^2(\alpha; k)},$$

where $\alpha \in (0, K(k))$ and $k \in (0, 1)$ are arbitrary parameters.

We can find explicitly

$$F_1 = \pm \sqrt{1 - k^2} \frac{\operatorname{sn}^2(\alpha; k)}{\operatorname{cn}^2(\alpha; k)},$$

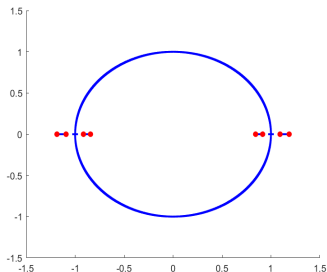
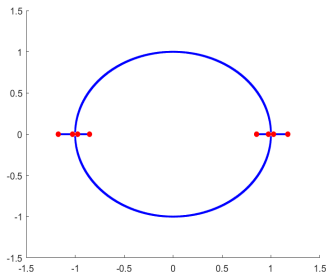
and

$$\lambda_1 = \frac{1}{\operatorname{cn}(\alpha; k)} \sqrt{(1 - \operatorname{sn}(\alpha; k)) \left(\operatorname{dn}(\alpha; k) - \sqrt{1 - k^2} \operatorname{sn}(\alpha; k) \right)},$$

$$\lambda_2 = \frac{1}{\operatorname{cn}(\alpha; k)} \sqrt{(1 - \operatorname{sn}(\alpha; k)) \left(\operatorname{dn}(\alpha; k) + \sqrt{1 - k^2} \operatorname{sn}(\alpha; k) \right)},$$

satisfying $0 < \lambda_1 < \lambda_2 < 1 < \lambda_2^{-1} < \lambda_1^{-1}$.

Lax spectrum for dnoidal waves



The spectrum is found numerically for $\alpha = K(k)/M$ with $u_{n+2M} = u_n$:

$$\begin{cases} \sqrt{1 + u_n^2} p_{n+1} + \sqrt{1 + u_{n-1}^2} p_{n-1} - (u_n - u_{n-1}) q_n = z p_n, \\ (u_n - u_{n-1}) p_n + \sqrt{1 + u_n^2} q_{n+1} + \sqrt{1 + u_{n-1}^2} q_{n-1} = z q_n, \end{cases}$$

where $z := \lambda + \lambda^{-1}$ and (p_n, q_n) is the eigenvector satisfying

$$p_n = \hat{p}_n(\theta) e^{i\theta n}, \quad q_n = \hat{q}_n(\theta) e^{i\theta n}, \quad p_{n+2M} = p_n, \quad q_{n+2M} = q_n,$$

Cnoidal periodic waves

These are solutions of the form

$$u_n(t) = \frac{k \operatorname{sn}(\alpha; k)}{\operatorname{dn}(\alpha; k)} \operatorname{cn}(\alpha n + ct; k), \quad c = \frac{2 \operatorname{sn}(\alpha; k)}{\operatorname{dn}(\alpha; k)}, \quad \omega = \frac{2 \operatorname{cn}(\alpha; k)}{\operatorname{dn}^2(\alpha; k)},$$

where $\alpha \in (0, K(k))$ and $k \in (0, 1)$ are arbitrary parameters.

We can find explicitly

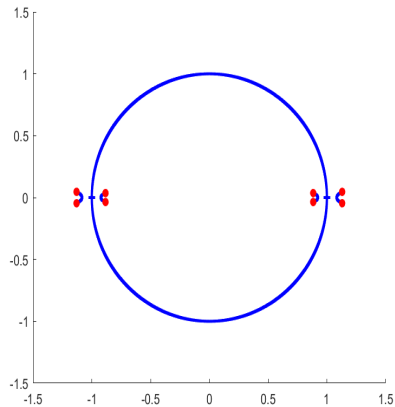
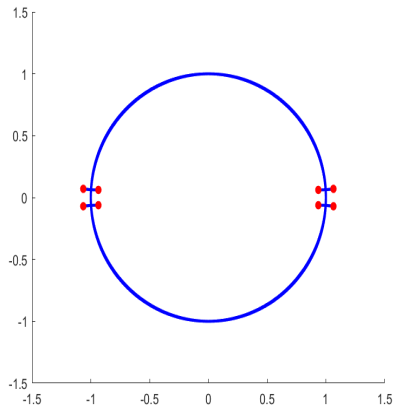
$$F_1 = \pm ik \sqrt{1 - k^2} \frac{\operatorname{sn}^2(\alpha; k)}{\operatorname{dn}^2(\alpha; k)}$$

and

$$\lambda_1 = \frac{\sqrt{(1 - k \operatorname{sn}(\alpha; k))(\operatorname{cn}(\alpha; k) + i \sqrt{1 - k^2} \operatorname{sn}(\alpha; k))}}{\operatorname{dn}(\alpha; k)},$$

satisfying $|\lambda_1| < 1 < |\lambda_1|^{-1}$.

Lax spectrum for cnoidal waves



Continuous modified KdV equation

Let $u(x, t) = \phi(x - ct)$ be a traveling periodic wave of the mKdV equation

$$u_t + 6u^2u_x + u_{xxx} = 0.$$

Let v be a perturbation of u satisfying the linearized mKdV equation

$$v_t + 6(u^2v)_x + v_{xxx} = 0,$$

which is obtained from mKdV after substituting $u + v$ to and neglecting v^2, v^3 .

Separating variables $v(x, t) = w(x - ct)e^{\gamma t}$, we obtain the spectral problem

$$\gamma w = \partial_x [-\partial_x^2 + c - 6u^2] w.$$

If $u(x + L) = u(x)$ is periodic, then by Floquet theory, $w(x + L) = w(x)e^{i\theta L}$, where $\theta \in [-\pi/L, \pi/L]$.

If there exists γ with $\text{Re}(\gamma) > 0$ for some $\theta \in [-\pi/L, \pi/L]$, then the standing periodic wave is spectrally unstable. It is modulationally unstable if the band with $\text{Re}(\gamma) > 0$ intersects $\gamma = 0$ as $\theta \rightarrow 0$.

Relation to squared eigenfunctions

Recall the linear Lax system:

$$\varphi_x = \begin{pmatrix} \lambda & u \\ -u & -\lambda \end{pmatrix} \varphi$$

and

$$\varphi_t = \begin{pmatrix} 4\lambda^3 + 2\lambda u^2 & 4\lambda^2 u + 2\lambda u_x + 2u^3 + u_{xx} \\ -4\lambda^2 u + 2\lambda u_x - 2u^3 - u_{xx} & -4\lambda^3 - 2\lambda u^2 \end{pmatrix} \varphi.$$

If $\varphi = (p, q)^T$ is a solution of the Lax system, then $v = p^2 - q^2$ is a solution of the linearized mKdV equation. By the same Floquet theory, the solution of the Lax system has the form

$$\varphi(x, t) = \psi(x - ct) e^{\Omega t},$$

where $\psi(x + L) = \psi(x) e^{\frac{1}{2}i\theta L}$. The squared eigenfunctions ψ determines the eigenfunction w of the spectral stability problem with $\gamma = 2\Omega$.

Relation to squared eigenfunctions

Theorem

Let λ belongs to the Lax spectrum of

$$\varphi_x = \begin{pmatrix} \lambda & u \\ -u & -\lambda \end{pmatrix} \varphi.$$

Then, $\Omega = \pm\sqrt{P(\lambda)}$, where $P(\lambda)$ is the characteristic polynomial for the traveling periodic waves:

$$P(\lambda) = 16\lambda^6 - 8c\lambda^4 + (4d + c^2)\lambda^2 - b^2.$$

Consequently, $\Lambda = 2\Omega = \pm 2\sqrt{P(\lambda)}$.

The proof follows from separation of variables for $\varphi_t = V(\lambda, u)\varphi$:

$$\begin{vmatrix} 4\lambda^3 + 2\lambda\phi^2 - c\lambda - \Omega & 4\lambda^2\phi + 2\lambda\phi' + 2\phi^3 + \phi'' - c\phi \\ -4\lambda^2\phi + 2\lambda\phi' - 2\phi^3 - \phi'' + c\phi & -4\lambda^3 - 2\lambda\phi^2 + c\lambda - \Omega \end{vmatrix} = 0.$$

Stability of the dnoidal periodic waves

$$u(x, t) = \operatorname{dn}(x - ct; k), \quad c = 2 - k^2, \quad L = 2K(k).$$

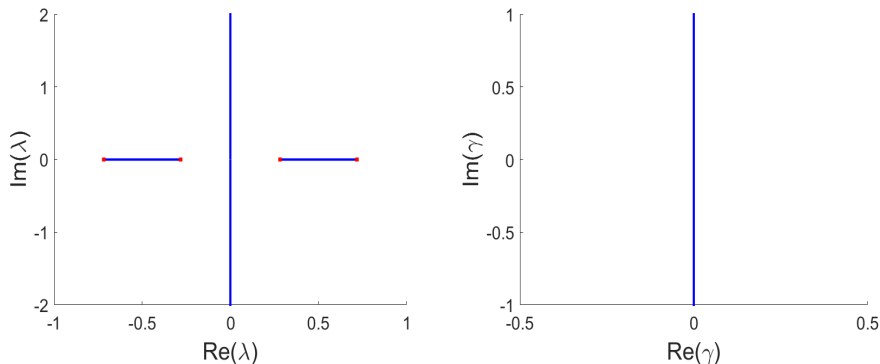


Figure: Lax spectrum (left) and stability spectrum (right) for $k = 0.9$ obtained with $\gamma = 2\Omega = \pm 2\sqrt{P(\lambda)}$.

Instability of the cnoidal periodic waves

$$u(x, t) = k \operatorname{cn}(x - ct; k), \quad c = 2k^2 - 1, \quad L = 4K(k).$$

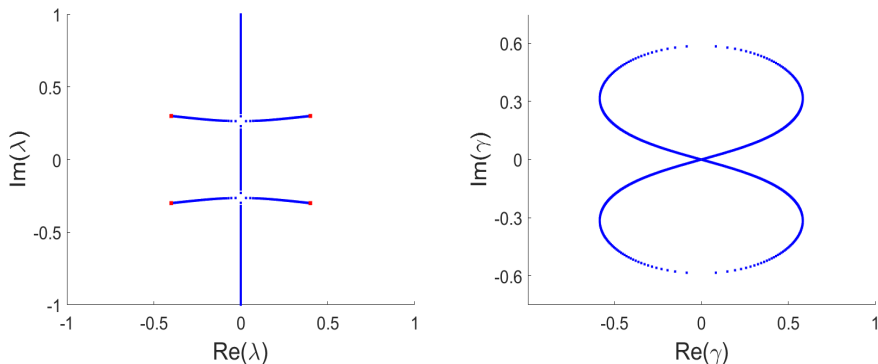


Figure: Lax spectrum (left) and stability spectrum (right) for the cnoidal wave with $k = 0.8$ obtained with $\gamma = 2\Omega = \pm 2\sqrt{P(\lambda)}$.

Instability of the cnoidal periodic waves

$$u(x, t) = k \operatorname{cn}(x - ct; k), \quad c = 2k^2 - 1, \quad L = 4K(k).$$

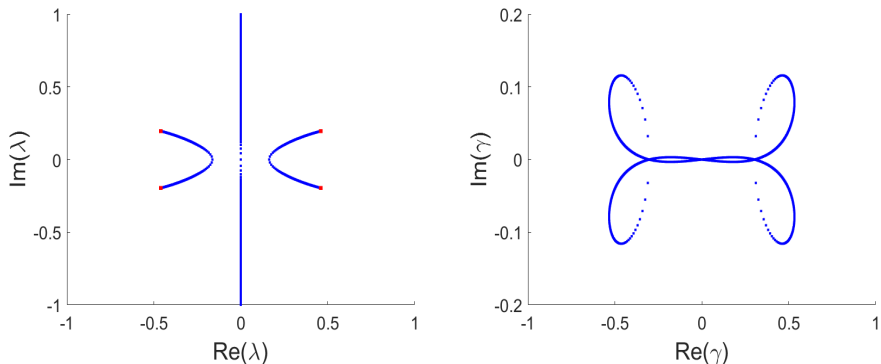


Figure: Lax spectrum (left) and stability spectrum (right) for the cnoidal wave with $k = 0.92$ obtained with $\gamma = 2\Omega = \pm 2\sqrt{P(\lambda)}$.

Discrete modified KdV equation

Let $u_n(t) = \phi(\alpha n + ct)$ be a traveling periodic wave of the discrete mKdV equation

$$\dot{u}_n = (1 + u_n^2)(u_{n+1} - u_{n-1}), \quad n \in \mathbb{Z}.$$

Let $\{v_n(t)\}_{n \in \mathbb{Z}}$ be a perturbation of $\{u_n(t)\}_{n \in \mathbb{Z}}$ satisfying the linearized mKdV equation

$$\dot{v}_n = (1 + u_n^2)(v_{n+1} - v_{n-1}) + 2u_n(u_{n+1} - u_{n-1})v_n, \quad n \in \mathbb{Z}.$$

We still have the squared eigenfunction relation:

$$v_n = \lambda p_n^2 - \lambda^{-1} q_n^2 + 2u_n p_n q_n,$$

where $\varphi_n = (p_n, q_n)^T$ is a solution of the linear Lax system.

Relation to squared eigenfunctions

Thus, $\{\varphi_n(t)\}_{n \in \mathbb{Z}}$ is a solution of the linear Lax system:

$$\varphi_{n+1} = \frac{1}{\sqrt{1 + u_n^2}} \begin{pmatrix} \lambda & u_n \\ -u_n & \lambda^{-1} \end{pmatrix} \varphi_n$$

and

$$\dot{\varphi}_n = \begin{pmatrix} \frac{1}{2}(\lambda^2 - \lambda^{-2}) & \lambda u_n + \lambda^{-1} u_{n-1} \\ -\lambda u_{n-1} - \lambda^{-1} u_n & -\frac{1}{2}(\lambda^2 - \lambda^{-2}) \end{pmatrix} \varphi_n,$$

with the obvious decomposition since $u_n(t) = \phi(\alpha n + ct)$:

$$\varphi_n(t) = \psi(\alpha n + ct) e^{\Omega t}.$$

However, the explicit relation between Ω and $P(\lambda)$ is missing!

$$P(\lambda) := \lambda^8 - 2\omega\lambda^6 + (2 + \omega^2 - 4F_1^2)\lambda^4 - 2\omega\lambda^2 + 1.$$

Stability of the dnoidal periodic waves

$$u_n(t) = \frac{\operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)} \operatorname{dn}(\alpha n + ct; k), \quad c = \frac{2\operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)},$$

where $\alpha \in (0, K(k))$ and $k \in (0, 1)$ are arbitrary parameters.

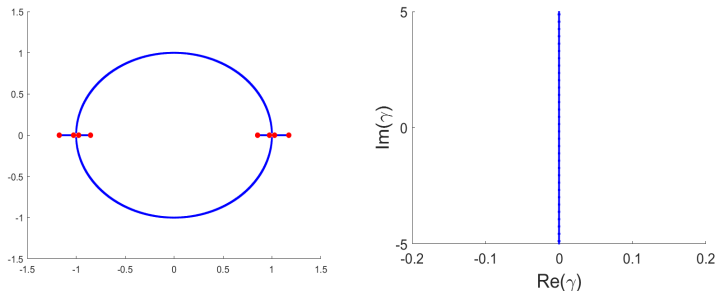


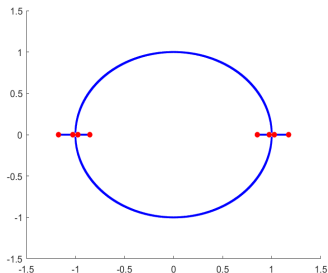
Figure: Lax spectrum (left) and stability spectrum (right) for $k = 0.7$ obtained numerically.

1-fold Darboux transformation

We can use eigenvalues found in the nonlinearization method to define a new solution to the discrete mKdV equation:

$$\hat{u}_n = -\frac{p_n^2 + \lambda_1^2 q_n^2}{\lambda_1^2 p_n^2 + q_n^2} u_n + \frac{(1 - \lambda_1^4) p_n q_n}{\lambda_1 (\lambda_1^2 p_n^2 + q_n^2)}$$

where $\varphi_n = (p_n, q_n)^T$ is a solution of Lax equations with $\lambda = \lambda_1$.



Trivial new solution

$$\varphi_{n+1} = \frac{1}{\sqrt{1+u_n^2}} \begin{pmatrix} \lambda & u_n \\ -u_n & \lambda^{-1} \end{pmatrix} \varphi_n$$

and

$$\dot{\varphi}_n = \begin{pmatrix} \frac{1}{2}(\lambda^2 - \lambda^{-2}) & \lambda u_n + \lambda^{-1} u_{n-1} \\ -\lambda u_{n-1} - \lambda^{-1} u_n & -\frac{1}{2}(\lambda^2 - \lambda^{-2}) \end{pmatrix} \varphi_n.$$

If $\varphi_n = (p_n, q_n)^T$ is obtained from $u_n = \lambda_1 p_n^2 + \lambda_1^{-1} q_n^2$ and λ_1 is a root of $P(\lambda)$, then new solution \hat{u}_n is a half-period translation of the dnoidal wave:

$$\begin{aligned} \hat{u}_n &= -F_1 u_n^{-1} \\ &= -\frac{\sigma_1 \operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)} \frac{\sqrt{1-k^2}}{\operatorname{dn}(\xi; k)} \\ &= -\frac{\sigma_1 \operatorname{sn}(\alpha; k)}{\operatorname{cn}(\alpha; k)} \operatorname{dn}(\xi + K(k); k) \\ &= -\sigma_1 u_n(t + c^{-1} K(k)). \end{aligned}$$

Nontrivial new solution

The second, linearly independent solution can be found in the form:

$$\hat{p}_n = p_n \theta_n - \frac{q_n}{p_n^2 + q_n^2}, \quad \hat{q}_n = q_n \theta_n + \frac{p_n}{p_n^2 + q_n^2},$$

where

$$\theta_{n+1} - \theta_n = \frac{(\lambda_1 + \lambda_1^{-1})^2 (u_n^2 - F_1)}{(u_n + u_{n-1})(u_n + u_{n+1})(1 + u_n^2)}$$

and

$$\dot{\theta}_n = \frac{(\lambda_1 + \lambda_1^{-1})^2 (u_n^2 + u_{n-1}^2 - 2F_1)}{(u_n + u_{n-1})^2}.$$

If $u_n(t) = \phi(\alpha n + ct)$ is the traveling wave with periodic ϕ , then $\theta_n(t) = an + bt + \chi(\alpha n + ct)$ with periodic χ and uniquely computed parameters a and b .

Algebraic soliton propagating on the dnoidal wave

The new solution is now nontrivial:

$$\hat{u}_n = -\frac{\hat{p}_n^2 + \lambda_1^2 \hat{q}_n^2}{\lambda_1^2 \hat{p}_n^2 + \hat{q}_n^2} u_n + \frac{(1 - \lambda_1^4) \hat{p}_n \hat{q}_n}{\lambda_1 (\lambda_1^2 \hat{p}_n^2 + \hat{q}_n^2)}$$

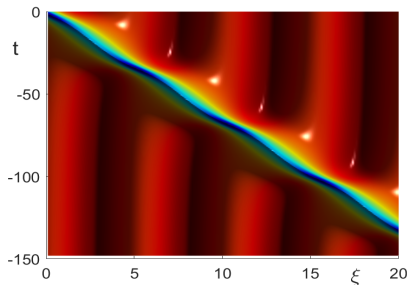
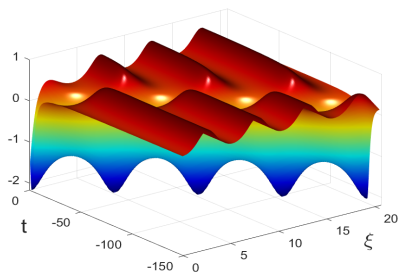


Figure: The solution surface (left: sideview, right: topview) for λ_1 .

Algebraic soliton propagating on the dnoidal wave

The new solution is now nontrivial:

$$\hat{u}_n = -\frac{\hat{p}_n^2 + \lambda_1^2 \hat{q}_n^2}{\lambda_1^2 \hat{p}_n^2 + \hat{q}_n^2} u_n + \frac{(1 - \lambda_1^4) \hat{p}_n \hat{q}_n}{\lambda_1 (\lambda_1^2 \hat{p}_n^2 + \hat{q}_n^2)}$$

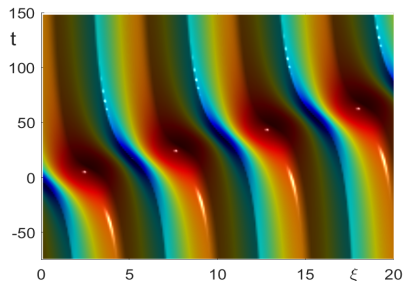
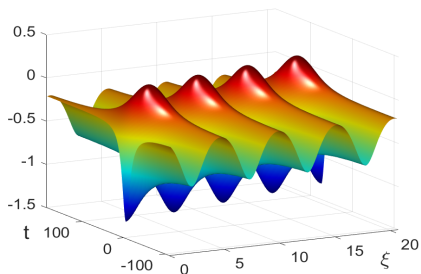


Figure: The solution surface (left: sideview, right: topview) for λ_2 .

2-fold Darboux transformation

The 2-fold transformation uses two eigenvalues λ_1 and λ_2 :

$$\hat{u}_n = \frac{\Upsilon_n}{\Delta_n} u_n - \frac{\Sigma_n}{\lambda_1 \lambda_2 \Delta_n},$$

where

$$\begin{aligned} \Upsilon_n &= \lambda_2^2(q_{2n}^2 + \lambda_2^2 p_{2n}^2)(p_{1n}^2 + \lambda_1^6 q_{1n}^2) + \lambda_1^2(q_{1n}^2 + \lambda_1^2 p_{1n}^2)(p_{2n}^2 + \lambda_2^6 q_{2n}^2) \\ &\quad - 2\lambda_1^2 \lambda_2^2 (p_{1n}^2 + \lambda_1^2 q_{1n}^2)(p_{2n}^2 + \lambda_2^2 q_{2n}^2) - 2p_{1n} q_{1n} p_{2n} q_{2n} \lambda_1 \lambda_2 (\lambda_1^4 - 1)(\lambda_2^4 - 1), \\ \Sigma_n &= (\lambda_1^2 - \lambda_2^2)(\lambda_1^2 \lambda_2^2 - 1)[\lambda_1(\lambda_2^4 - 1)p_{2n} q_{2n}(q_{1n}^2 + \lambda_1^2 p_{1n}^2) \\ &\quad - \lambda_2(\lambda_1^4 - 1)p_{1n} q_{1n}(q_{2n}^2 + \lambda_2^2 p_{2n}^2)], \\ \Delta_n &= (\lambda_1^2 \lambda_2^2 - 1)^2 (\lambda_1^2 p_{1n}^2 q_{2n}^2 + \lambda_2^2 p_{2n}^2 q_{1n}^2) + (\lambda_1^2 - \lambda_2^2)^2 (\lambda_1^2 \lambda_2^2 p_{1n}^2 p_{2n}^2 + q_{1n}^2 q_{2n}^2) \\ &\quad - 2p_{1n} q_{1n} p_{2n} q_{2n} \lambda_1 \lambda_2 (\lambda_1^4 - 1)(\lambda_2^4 - 1). \end{aligned}$$

Two algebraic solitons on the dnoidal wave

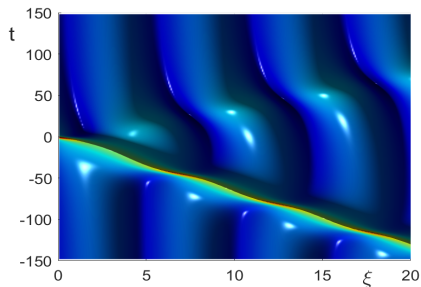
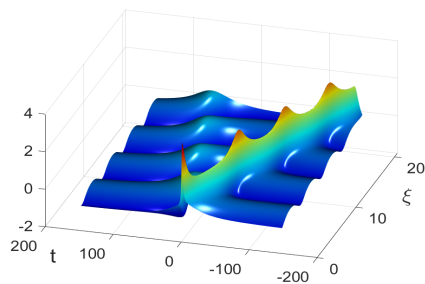


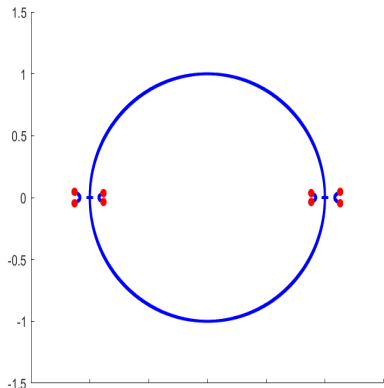
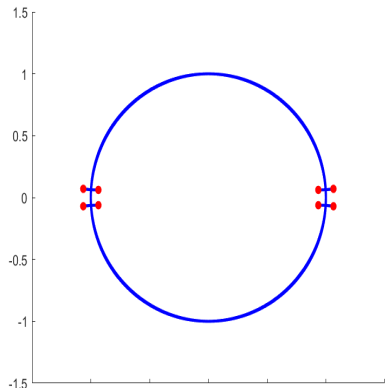
Figure: The solution surface (left: sideview, right: topview) for eigenvalues λ_1 and λ_2 .

Similar new solutions for the cnoidal wave

For the cnoidal wave, the new solution after 2-fold transformation is real valued if $\lambda_2 = \bar{\lambda}_1$. However, $p_n^2 + q_n^2$ is not sign-definite and the representation

$$\hat{p}_n = p_n \theta_n - \frac{q_n}{p_n^2 + q_n^2}, \quad \hat{q}_n = q_n \theta_n + \frac{p_n}{p_n^2 + q_n^2}$$

cannot be used.



Another representation

The second, linearly independent solution can be found in the form:

$$\hat{p}_n = p_n \theta_n - \frac{1}{2q_n}, \quad \hat{q}_n = q_n \theta_n + \frac{1}{2p_n},$$

where

$$\theta_{n+1} - \theta_n = \frac{(\lambda_1^2 - \lambda_1^{-2})^2 u_n^2}{2(1 + u_n^2)(F_1 - u_n u_{n-1})(F_1 - u_{n+1} u_n)}$$

and

$$\dot{\theta}_n = \frac{(\lambda_1^2 - \lambda_1^{-2})^2 u_n u_{n-1}}{(F_1 - u_n u_{n-1})^2},$$

If $u_n(t) = \phi(\alpha n + ct)$ is the traveling wave with periodic ϕ , then $\theta_n(t) = an + bt + \chi(\alpha n + ct)$ with periodic χ and uniquely computed parameters a and b .

Rogue wave on the cnoidal wave

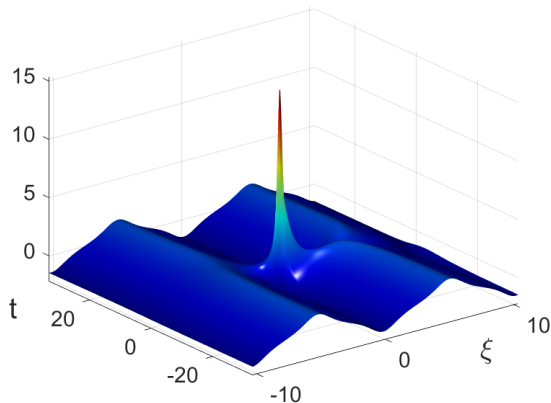


Figure: The solution surface for eigenvalues λ_1 and $\lambda_2 = \bar{\lambda}_1$.

Summary

- Traveling periodic waves are recovered from the nonlinearization method based on the constraint $u_n = \lambda_1 p_n^2 + \lambda_1^{-1} q_n^2$ with λ_1 being a root of $P(\lambda)$.
- Dnoidal waves are spectrally (modulationally) stable, whereas cnoidal waves are spectrally (modulationally) unstable.
- Only two distinct algebraic solitons exist on the background of dnoidal waves. A rogue wave exists on the background of cnoidal waves.
- Two open questions include
 - 1 relation between $(1 + u_n^2)(u_{n+1} + u_{n-1}) = \omega u_n$ and $\dot{u}_n = (1 + u_n^2)(u_{n+1} - u_{n-1})$
 - 2 connection between $P(\lambda)$ and the stability spectrum Ω .

Many thanks for your attention!