# Justification of the KP-II approximation in dynamics of two-dimensional FPU systems 

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#### Abstract

Dynamics of the Fermi-Pasta-Ulam (FPU) system on a two-dimensional square lattice is considered in the limit of small-amplitude long-scale waves with slow transverse modulations. In the absence of transverse modulations, dynamics of such waves, even at an oblique angle with respect to the square lattice, is known to be described by the Korteweg-de Vries (KdV) equation. For the three basic directions (horizontal, vertical, and diagonal), we prove that the modulated waves are well described by the Kadomtsev-Petviashvili (KP-II) equation. The result was expected long ago but proving rigorous bounds on the approximation error turns out to be complicated due to the nonlocal terms of the KP-II equation and the vector structure of the FPU systems on two-dimensional lattices. We have obtained these error bounds by extending the local well-posedness result for the KP-II equation in Sobolev spaces and by controlling the error terms with energy estimates. The bounds are useful in the analysis of transverse stability of solitary and periodic waves in two-dimensional FPU systems due to many results available for the KP-II equation.


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## 1. Introduction

A Fermi-Pasta-Ulam (FPU) system is formed by particles connected to their nearest neighbours by nonlinear springs. If the particles are organized in a one-dimensional chain, we can label the position variable of the $j$-th particle by $q_{j}$. The equations of motion are written in the form

$$
\begin{equation*}
\ddot{q}_{j}=V^{\prime}\left(q_{j+1}-q_{j}\right)-V^{\prime}\left(q_{j}-q_{j-1}\right), \tag{1.1}
\end{equation*}
$$

where $V(q)$ is the potential energy. The total conserved energy of the FPU system (1.1) is given by

$$
\begin{equation*}
H=\sum_{j \in \mathbb{Z}} \frac{1}{2} \dot{q}_{j}^{2}+V\left(q_{j+1}-q_{j}\right) \tag{1.2}
\end{equation*}
$$

A useful approximation to dynamics of small-amplitude long-scale waves in the FPU chain with smooth $V$ satisfying $V^{\prime}(0)=0, V^{\prime \prime}(0)>0$, and $V^{\prime \prime \prime}(0) \neq 0$ is given by the Korteweg-de Vries (KdV) equation, which is a remarkable model due to integrability, stability of periodic and solitary waves, and global existence of solutions in Sobolev spaces (see [18] for review).

Bounds on the approximation error between solutions of the FPU system and the KdV equation were obtained by G. Schneider and C.E. Wayne in a conference proceeding [31] as an exercise related to the justification technique the authors had developed for the water wave problem [32]. The same approximation appeared to be very useful in the context of stability of FPU solitary waves and was studied comprehensively in the series of papers by G. Friesecke and R. L. Pego [13-16]. It was also justified in the context of normal forms and KAM theory for metastability and recurrency of the FPU systems $[2,30]$.

More recently, the same approximation but with other versions of the KdV equation was justified for FPU systems with Hertzian potentials [9] and with pure anharmonic powers [26]. In [26], the KdV approximation was extended to logarithmically long time scales provided the global dynamics of the
generalized KdV equation is well defined in Sobolev spaces of higher regularity. The KdV approximation was also used in the context of periodic waves and for FPU systems with nonlocal interactions [12,24]. Higher-order corrections to the KdV approximation were studied in [21], where it was shown that the second-order corrections are spanned by two members of the integrable KdV hierarchy, whereas the thirdorder corrections can only be spanned by three members of the KdV hierarchy under a constraint on parameters of the FPU system. Review of results on nonlinear waves in one-dimensional FPU chains can be found in [37].

The purpose of this work is to consider dynamics of the two-dimensional FPU systems and to justify the two-dimensional KdV approximation given by the Kadomtsev-Petviashvili (KP-II) equation. Similar to the KdV equation, the KP-II equation is remarkable due to integrability [40], stability of periodic and solitary waves [23,28], and global existence of solutions in Sobolev spaces [22,29].

The first formal derivation of the KP-II equation was performed in [10] for the scalar extension of the two-dimensional FPU systems with the total energy of the form

$$
\begin{equation*}
H=\sum_{(j, k) \in \mathbb{Z}^{2}} \frac{1}{2} \dot{q}_{j, k}^{2}+\frac{1}{2}\left(q_{j+1, k}-q_{j, k}\right)^{2}+\frac{1}{2} \varepsilon^{2}\left(q_{j, k+1}-q_{j, k}\right)^{2}+\frac{1}{3} \alpha\left(q_{j+1, k}-q_{j, k}\right)^{3}, \tag{1.3}
\end{equation*}
$$

where $\varepsilon^{2}$ is a small parameter of slow transverse modulations in the $k$-direction of the dominant wave propagating in the $j$ direction and $\alpha$ is the parameter for the cubic interaction potential. A similar scalar model was considered in the recent work [20], where the KP-II equation in the periodic domain was rigorously justified (among other integrable models) as the normal form for metastability (exponential localization of energy) [5] in two-dimensional rectangular lattices. Existence of two-dimensional solitary waves [7] and breathers (space-localized and time-periodic solutions) $[38,39]$ was also studied in the scalar two-dimensional FPU lattices. Extensions of the scalar two-dimensional FPU models that include harmonic interactions between the first and second nearest neighbours were considered in [1,25]. Applications of the scalar FPU models to the two-dimensional square-packed granular arrays were studied numerically and experimentally in [27], where propagation of a modulated one-dimensional solitary wave was observed. Periodic triangular lattices were compared with square lattices in the numerical study in [3, 4], where it was shown that non-square lattices do not have integrable approximations leading to the energy localization.

In the context of mechanical models of the elasticity theory, vector extensions of the two-dimensional FPU systems were considered but the long-wave reductions were used to derive the one-dimensional KdV equation (rather than the two-dimensional KP-II equation). A two-dimensional square FPU lattice was considered in [11] with additional springs along the diagonals and a pair of potential functions, one for the horizontal and vertical displacements and the other one for the diagonal displacements. Existence of small-amplitude supersonic longitudinal solitary waves propagating along the horizontal direction was proven in [11]. Surprisingly, the result holds even when the potential functions are quadratic, due to the geometric nonlinearity of the lattice. Nonlinear couplings were included in the consideration of the same model in [8], where the solitary wave propagated under an arbitrary angle with respect to the square lattice.

Another work can be found in [33], where propagation of rings in two-dimensional lattices was analysed in the linear approximation and compared rigorously with the approximation of the linearized KdV equation (rather than with the linearized KP-II equation).

Compared to the previous works, we prove validity of the KP-II approximation for dynamics of transversely modulated small-amplitude long-scale waves in a vector FPU system on a two-dimensional square lattice.

The paper is organized as follows. Section 2 presents the mechanical models and the main results of this work. Section 3 contains preliminary results needed for the justification analysis. In particular, we extend [19] to obtain additional estimates on solutions of the KP-II equation and extend [9,31] to control $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm at the slowly varying solution of the KP-II equation. Section 4 gives the proof of Theorem

1 after equations of motion are set up in the strain variables and the near-identity transformations are performed to reduce the residual. The error terms are controlled from the energy estimates and Gronwall's inequality. Section 5 gives relevant details for the proof of Theorem 2. Summary and discussion of further questions are contained in the concluding Sect. 6.

## 2. Main results

For the mechanical model, each particle at the $(j, k)$ site of the two-dimensional square lattice is characterized by the vectors of relative displacements $\left(x_{j, k}, y_{j, k}\right)$ and relative velocities $\left(\dot{x}_{j, k}, \dot{y}_{j, k}\right)$. The nonlinear springs connecting the particles are shown on Fig. 1. The potential energy of a single spring between two particles in the horizontal direction is defined by

$$
V(r, s)=\frac{1}{2} c_{1}^{2} r^{2}+\frac{1}{2} c_{2}^{2} s^{2}+\frac{1}{3} \alpha_{1} r^{3}+\frac{1}{2} \alpha_{2} r s^{2},
$$

where $(r, s)$ are the relative displacements of the two particles in the $(x, y)$ coordinates, $\left(c_{1}^{2}, c_{2}^{2}\right)$ are some coefficients of the quadratic interaction potential, and ( $\alpha_{1}, \alpha_{2}$ ) are some coefficients of the cubic interaction potential. The cubic terms are chosen in such a way that the potential energy of the horizontal spring is symmetric with respect to the sign of vertical relative displacements of the particles. Due to the symmetry between horizontal and vertical springs, the total energy of the two-dimensional FPU lattice takes the form

$$
\begin{align*}
H=\frac{1}{2} & \sum_{(j, k) \in \mathbb{Z}^{2}} \dot{x}_{j, k}^{2}+\dot{y}_{j, k}^{2} \\
& +\sum_{(j, k) \in \mathbb{Z}^{2}} V\left(x_{j+1, k}-x_{j, k}, y_{j+1, k}-y_{j, k}\right)+V\left(y_{j, k+1}-y_{j, k}, x_{j, k+1}-x_{j, k}\right) . \tag{2.1}
\end{align*}
$$



Fig. 1. A mass-spring mechanical system arranged in a square lattice

The corresponding equations of motion are given by

$$
\begin{align*}
\ddot{x}_{j, k}= & V_{x}\left(x_{j+1, k}-x_{j, k}, y_{j+1, k}-y_{j, k}\right)-V_{x}\left(x_{j, k}-x_{j-1, k}, y_{j, k}-y_{j-1, k}\right) \\
& +V_{y}\left(y_{j, k+1}-y_{j, k}, x_{j, k+1}-x_{j, k}\right)-V_{y}\left(y_{j, k}-y_{j, k-1}, x_{j, k}-x_{j, k-1}\right), \tag{2.2}
\end{align*}
$$

and

$$
\begin{align*}
\ddot{y}_{j, k}= & V_{y}\left(x_{j+1, k}-x_{j, k}, y_{j+1, k}-y_{j, k}\right)-V_{y}\left(x_{j, k}-x_{j-1, k}, y_{j, k}-y_{j-1, k}\right) \\
& +V_{x}\left(y_{j, k+1}-y_{j, k}, x_{j, k+1}-x_{j, k}\right)-V_{x}\left(y_{j, k}-y_{j, k-1}, x_{j, k}-x_{j, k-1}\right), \tag{2.3}
\end{align*}
$$

where $V_{x}$ and $V_{y}$ denote partial derivatives of $V=V(x, y)$.
As is discussed in [17], the model with horizontal and vertical springs may not capture all properties of elastic materials and diagonal springs are required to describe structural stability of some materials. The KP-II approximation in the square lattices with additional diagonal springs should be possible, but computations of coefficients will become more complicated.

Next we present the main result for the propagation of nonlinear waves in the horizontal direction. We will seek a continuous approximating function of the form

$$
\begin{equation*}
x_{j, k}=\varepsilon X(\xi, \eta, \tau)+\text { error, } \tag{2.4}
\end{equation*}
$$

with $\xi=\varepsilon\left(j-c_{1} t\right), \eta=\varepsilon^{2} k$, and $\tau=\varepsilon^{3} t$. We will show that $x_{j, k}$ satisfy the equations of motion with small error controllable in $\ell^{2}\left(\mathbb{Z}^{2}\right)$ if $X(\xi, \eta, \tau)$ solves the following KP-II equation

$$
\begin{equation*}
2 c_{1} \partial_{\xi} \partial_{\tau} X+\frac{c_{1}^{2}}{12} \partial_{\xi}^{4} X+2 \alpha_{1}\left(\partial_{\xi} X\right)\left(\partial_{\xi}^{2} X\right)+c_{2}^{2} \partial_{\eta}^{2} X=0 \tag{2.5}
\end{equation*}
$$

For justification analysis, it is more convenient to solve the FPU system in strain variables,

$$
\left\{\begin{array}{l}
u_{j, k}^{(1)}:=x_{j+1, k}-x_{j, k},  \tag{2.6}\\
u_{j, k}^{(2)}:=x_{j, k+1}-x_{j, k}, \\
v_{j, k}^{(1)}:=y_{j+1, k}-y_{j, k}, \\
v_{j, k}^{(2)}:=y_{j, k+1}-y_{j, k},
\end{array}\right.
$$

which are defined by the relative displacements between adjacent particles, and introduce the amplitude function $A(\xi, \eta, \tau)$ in the form

$$
\begin{equation*}
x_{j+1, k}-x_{j, k}=\varepsilon^{2} A(\xi, \eta, \tau)+\text { error. } \tag{2.7}
\end{equation*}
$$

The reason for the different scaling in (2.4) and (2.7) is that we can formally consider the relationship between the function $A$ and $X$ through a Taylor expansion

$$
\begin{equation*}
A(\xi, \eta, \tau)=\partial_{\xi} X(\xi, \eta, \tau)+\mathcal{O}(\varepsilon) \tag{2.8}
\end{equation*}
$$

so that the KP-II equation (2.5) can be rewritten in the form

$$
\begin{equation*}
2 c_{1} \partial_{\xi} \partial_{\tau} A+\frac{c_{1}^{2}}{12} \partial_{\xi}^{4} A+2 \alpha_{1} \partial_{\xi}\left(A \partial_{\xi} A\right)+c_{2}^{2} \partial_{\eta}^{2} A=0 \tag{2.9}
\end{equation*}
$$

Associated with a smooth solution to the KP-II equation (2.9) at a given time $\tau$, for which both $A \in$ $H^{s}\left(\mathbb{R}^{2}\right)$ and $\partial_{\xi}^{-1} A \in H^{s}\left(\mathbb{R}^{2}\right)$ with sufficiently large $s$, we define the anti-derivative by

$$
\partial_{\xi}^{-1} A(\xi, \eta):=\int_{-\infty}^{\xi} A\left(\xi^{\prime}, \eta\right) d \xi^{\prime}
$$

The solution to the KP-II equation (2.9) is required to have enough regularity so that $\partial_{\xi}^{-1} \partial_{\tau}^{2} A \in$ $C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\left(\mathbb{R}^{2}\right)\right)$ and $\partial_{\xi}^{-2} \partial_{\eta}^{2} \partial_{\tau} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\left(\mathbb{R}^{2}\right)\right)$ with $s \geq 3$. Existence of such solutions is proven in Lemma 1 (Section 3). Since $A\left(\varepsilon\left(j-c_{1} t\right), \varepsilon^{2} k, \varepsilon^{3} t\right)$ is estimated in the $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm over
$(j, k) \in \mathbb{Z}^{2}$, we will also need the bound on the $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm of these terms by their $H^{s}\left(\mathbb{R}^{2}\right)$ norm, this bound is obtained in Lemma 2 (Sect. 3).

The following theorem formulates the main result which justifies the KP-II approximation (2.9) for the horizontal propagation of nonlinear waves.
Theorem 1. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\left(\mathbb{R}^{2}\right)\right)$ be a solution to the KP-II equation (2.9) with fixed $s \geq 0$, whose initial data $A(\xi, \eta, 0)=A_{0}$ satisfies

$$
A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right), \quad \partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)
$$

and

$$
\partial_{\xi}^{-1} \partial_{\eta}^{2}\left[\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0}+A_{0}^{2}\right] \in H^{s+3}\left(\mathbb{R}^{2}\right)
$$

Then, there are constants $C_{0}, C_{1}, \varepsilon_{0}>0$ such that for $\varepsilon \in\left(0, \varepsilon_{0}\right)$ if the initial conditions of the twodimensional FPU system satisfies

$$
\begin{align*}
& \left\|u_{i n}^{(1)}-\varepsilon^{2} A_{0}\right\|_{\ell^{2}}+\left\|u_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|\dot{x}_{i n}+\varepsilon^{2} c_{1} A_{0}\right\|_{\ell^{2}} \\
& +\left\|v_{i n}^{(1)}\right\|_{\ell^{2}}+\left\|v_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|\dot{y}_{i n}\right\|_{\ell^{2}} \leq C_{0} \varepsilon^{\frac{5}{2}} \tag{2.10}
\end{align*}
$$

then the solution to the two-dimensional FPU system satisfies

$$
\begin{align*}
& \left\|u^{(1)}(t)-\varepsilon^{2} A\right\|_{\ell^{2}}+\left\|u^{(2)}(t)\right\|_{\ell^{2}}+\left\|\dot{x}(t)+\varepsilon^{2} c_{1} A\right\|_{\ell^{2}} \\
& +\left\|v^{(1)}(t)\right\|_{\ell^{2}}+\left\|v^{(2)}(t)\right\|_{\ell^{2}}+\|\dot{y}(t)\|_{\ell^{2}} \leq C_{1} \varepsilon^{\frac{5}{2}}, \tag{2.11}
\end{align*}
$$

for $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Remark 1. Extending this result to $\varepsilon^{\frac{7}{2}}$ is difficult as the next order of the asymptotic expansion has terms which are not removed by seeking solutions to the KP-II equation alone. They could be removed by seeking a function of the form

$$
A(\xi, \eta, \tau)=A^{(0)}(\xi, \eta, \tau)+\varepsilon^{2} A^{(1)}(\xi, \eta, \tau),
$$

where $A^{(0)}$ solves the KP-II equation (2.9) and $A^{(1)}$ solves an appropriately chosen linearized KP-II equation. However, the linearized KP-II equation is nonhomogeneous, where the nonhomogeneous piece contains higher-order antiderivative terms of $A^{(0)}$.

Remark 2. Compared to the work [10], the slow transverse modulations in the expansion (2.7) are not due to the external small parameter in the potential energy $V(r, s)$. If we have the external small parameter $\varepsilon$ as in (1.3), we can use $\eta=\varepsilon k$ so that the comparison between the $\ell^{2}$ norm and the Sobolev norm would only lose $\varepsilon^{-1}$ compared to $\varepsilon^{-\frac{3}{2}}$ in Lemma 2. Performing the justification analysis on a version of the FPU system as in [10] should also yield Theorem 1 but with the errors bounds of $\varepsilon^{3}$ rather than $\varepsilon^{\frac{5}{2}}$.

Remark 3. Theorem 1 can be proven in the setting of periodic transverse modulations, for which $A(\xi, \eta+$ $P, \tau)=A(\xi, \eta, \tau)$ with fixed $P>0$. In view of the scaling $\eta=\varepsilon^{2} k$, this would correspond to the periodic transverse modulations with large, $\varepsilon$-dependent period $P \varepsilon^{-2}$. Similarly, one can consider periodic waves of the KP-II equation satisfying $A(\xi+L, \eta, \tau)=A(\xi, \eta, \tau)$, for which the periodic waves of the FPU lattice has large, $\varepsilon$-dependent period $L \varepsilon^{-1}$. The recent work [20] addresses the KP-II approximation for periodic solutions in both spatial directions of the rectangular FPU system as the normal form which justifies rigorously the exponential localization of energy for the initial data of a long wavelength also known as the metastability phenomenon [5].

Remark 4. By the obvious symmetry, the result of Theorem 1 can be formulated for the vertical propagation of nonlinear waves in the $y$-coordinates.


FIG. 2. A diatomic mass spring system arranged in a square lattice

Finally, we consider the diagonal propagation of nonlinear waves in the FPU lattice shown on Fig. 1 and introduce a new coordinate system by

$$
m=\frac{j+k}{2}, \quad n=\frac{j-k}{2}, \quad(j, k) \in \mathbb{Z}^{2} .
$$

In the new coordinate system, the particle experiences nearest-neighbour interactions with neighbours located a half lattice site away. Due to this we redefine $x_{j, k}$ as $x_{m, n}$ and introduce $\chi_{m, n}:=x_{m+\frac{1}{2}, n+\frac{1}{2}}$. The FPU system becomes a diatomic system where $x_{m, n}$ particles communicate with four $\chi_{m, n}$ nearestneighbour particles and vice versa, see Fig. 2 for an illustration.

We will seek a continuous approximating function of the form

$$
x_{m, n}=\varepsilon X\left(\varepsilon\left(m-c_{1}^{*} t\right), \varepsilon^{2}\left(n-c_{2}^{*} t\right), \varepsilon^{3} t\right)+\text { error },
$$

where $c_{1}^{*}=\frac{1}{2} \sqrt{c_{1}^{2}+c_{2}^{2}}$ and $c_{2}^{*}=\frac{1}{2} \sqrt{c_{1}^{2}-c_{2}^{2}}$. It is hard to control the error in a general case because nonlocal terms related to the solution of the KP-II equation appear in lower-orders of the asymptotic approximation. However, if $c_{2}=c_{1}$ and $\alpha_{2}=2 \alpha_{1}$, then $c_{1}^{*}=\frac{c_{1}}{\sqrt{2}}, c_{2}^{*}=0$ and furthermore, the FPU system is satisfied by the invariant reduction $x_{j, k}=y_{j, k}$. By using the strain variables,

$$
\begin{equation*}
x_{m+1, n}-x_{m, n}=\varepsilon^{2} A\left(\varepsilon\left(m-c_{1}^{*} t\right), \varepsilon^{2} n, \varepsilon^{3} t\right)+\text { error } \tag{2.12}
\end{equation*}
$$

which corresponds to the displacement along the main diagonal, we derive the following KP-II equation for $A(\xi, \eta, \tau)$ with the same relation (2.8) between $A$ and $\partial_{\xi} X$ :

$$
\begin{equation*}
2 c_{1}^{*} \partial_{\xi} \partial_{\tau} A+\frac{\left(c_{1}^{*}\right)^{2}}{48} \partial_{\xi}^{4} A+\alpha_{1} \partial_{\xi}\left(A \partial_{\xi} A\right)+\left(c_{1}^{*}\right)^{2} \partial_{\eta}^{2} A=0 \tag{2.13}
\end{equation*}
$$

where $\xi=\varepsilon\left(m-c_{1}^{*} t\right), \eta=\varepsilon^{2} n$, and $\tau=\varepsilon^{3} t$. Similarly to the case of horizontal propagation, we can redefine the strain variables for the diagonal propagation as follows:

$$
\left\{\begin{array}{l}
u_{m, n}^{(1)}:=x_{m+1, n}-x_{m, n},  \tag{2.14}\\
u_{m, n}^{(2)}:=x_{m, n+1}-x_{m, n}, \\
v_{m, n}^{(1)}:=\chi_{m+1, n}-\chi_{m, n}, \\
v_{m, n}^{(2)}:=\chi_{m, n+1}-\chi_{m, n} .
\end{array}\right.
$$

The following theorem is similar to Theorem 1 but it justifies the KP-II approximation (2.13) for the diagonal propagation of nonlinear waves.

Theorem 2. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\left(\mathbb{R}^{2}\right)\right)$ be a solution to the KP-II equation (2.13) with fixed $s \geq 0$, whose initial data $A(\xi, \eta, 0)=A_{0}$ satisfies

$$
A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right), \quad \partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)
$$

and

$$
\partial_{\xi}^{-1} \partial_{\eta}^{2}\left[\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0}+A_{0}^{2}\right] \in H^{s+3}\left(\mathbb{R}^{2}\right)
$$

Then, there are constants $C_{0}, C_{1}, \varepsilon_{0}>0$ such that for $\varepsilon \in\left(0, \varepsilon_{0}\right)$ if the initial conditions of the twodimensional FPU system with $c_{2}=c_{1}$ and $\alpha_{2}=2 \alpha_{1}$ satisfies

$$
\begin{align*}
& \left\|u_{i n}^{(1)}-\varepsilon^{2} A_{0}\right\|_{\ell^{2}}+\left\|u_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|\dot{x}_{i n}+\varepsilon^{2} c_{1}^{*} A_{0}\right\|_{\ell^{2}} \\
& +\left\|v_{i n}^{(1)}-\varepsilon^{2} A_{0}\right\|_{\ell^{2}}+\left\|v_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|\dot{\chi}_{i n}+\varepsilon^{2} c_{1}^{*} A_{0}\right\|_{\ell^{2}} \leq C_{0} \varepsilon^{\frac{5}{2}} \tag{2.15}
\end{align*}
$$

then the solution to the two-dimensional FPU system satisfies

$$
\begin{align*}
& \left\|u^{(1)}(t)-\varepsilon^{2} A\right\|_{\ell^{2}}+\left\|u^{(2)}(t)\right\|_{\ell^{2}}+\left\|\dot{x}(t)+\varepsilon^{2} c_{1}^{*} A\right\|_{\ell^{2}} \\
& +\left\|v^{(1)}(t)-\varepsilon^{2} A\right\|_{\ell^{2}}+\left\|v^{(2)}(t)\right\|_{\ell^{2}}+\left\|\dot{\chi}(t)+\varepsilon^{2} c_{1}^{*} A\right\|_{\ell^{2}} \leq C_{1} \varepsilon^{\frac{5}{2}}, \tag{2.16}
\end{align*}
$$

for $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Remark 5. It is an open problem to justify the KP-II approximation for diagonal propagation with $c_{2} \neq c_{1}$ and $\alpha_{2} \neq 2 \alpha_{1}$ or for other directions along the lattice. The main challenge arises in controlling in Sobolev norm of the nonlocal terms computed at solutions of the KP-II equation. Even for Theorem 2, if we use another equivalent choice for the asymptotic approximation, e.g.

$$
\begin{equation*}
\chi_{m, n}-x_{m, n}=\frac{1}{2} \varepsilon^{2} A\left(\varepsilon\left(m-c_{1}^{*} t\right), \varepsilon^{2} n, \varepsilon^{3} t\right)+\text { error }, \tag{2.17}
\end{equation*}
$$

the asymptotic expansions contain some nonlocal terms. Although these nonlocal terms can be transformed away by near-identity transformations, the choice of (2.12) allows us to avoid the nonlocal terms, see Sect. 5.

## 3. Preliminary results

Consider the Cauchy problem for the normalized KP-II equation

$$
\left\{\begin{array}{l}
\partial_{\tau} A+\partial_{\xi}\left(A^{2}\right)+\partial_{\xi}^{3} A+\partial_{\xi}^{-1} \partial_{\eta}^{2} A=0, \quad t>0  \tag{3.1}\\
\left.A\right|_{\tau=0}=A_{0}
\end{array}\right.
$$

The normalized KP-II equation differs slightly from (2.9) and (2.13), in the choice of constants. However, the constants in the KP-II equation can be changed, as long as each constant is positive, through a scaling of its variables.

Global well-posedness of the Cauchy problem (3.1) was established in $H^{s}\left(\mathbb{T}^{2}\right)$ or $H^{s}\left(\mathbb{R}^{2}\right)$ with any $s \geq 0$ in [6], provided that the initial data satisfies the constraint

$$
\begin{equation*}
\int_{\mathbb{R}} A_{0}(\xi, \eta) d \xi=0, \quad \text { for every } \eta \tag{3.2}
\end{equation*}
$$

The result was proven by combining local well-posedness and conservation laws, namely conservation of the $L^{2}$ norm along the solution.

Local well-posedness result was extended in [35] to Sobolev spaces of the type $H^{s_{1}, s_{2}}\left(\mathbb{R}^{2}\right)$, with $s_{1}>-\frac{1}{4}$ and $s_{2} \geq 0$, the global result was also obtained by the conservation laws provided that $s_{1} \geq 0$. It was further shown in [34] that the zero-mean constraint (3.2) can be dropped in the local well-posedness result.

We will use the following local well-posedness result [19] (see [36] for earlier work).
Proposition 1. [19] For any $A_{0} \in H^{s+6}\left(\mathbb{R}^{2}\right)$ such that $\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0} \in H^{s+6}\left(\mathbb{R}^{2}\right)$ with fixed $s \geq 0$, there exists $\tau_{0}>0$ such that the Cauchy problem (3.1) admits a unique solution

$$
A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+6}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right) \cap C^{2}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\right)
$$

such that $\partial_{\xi}^{-1} \partial_{\eta} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+5}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+2}\right)$.
However, for our work, we need to extend this result to $C^{3}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\right)$ since we need the antiderivative term $\partial_{\xi}^{-1} A$ as a function of $\tau$ to be twice continuously differentiable in some Sobolev space. The following lemma presents the corresponding extension of Proposition 1.

Lemma 1. For any $A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)$ such that $\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)$ and

$$
\partial_{\xi}^{-1} \partial_{\eta}^{2}\left[\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0}+A_{0}^{2}\right] \in H^{s+3}\left(\mathbb{R}^{2}\right)
$$

with fixed $s \geq 0$, there exists $\tau_{0}>0$ such that the Cauchy problem (3.1) admits a unique solution

$$
A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+6}\right) \cap C^{2}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right) \cap C^{3}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\right)
$$

such that

$$
\partial_{\xi}^{-1} \partial_{\eta} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+8}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+5}\right) \cap C^{2}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+2}\right)
$$

and

$$
\partial_{\xi}^{-2} \partial_{\eta}^{2} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+6}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right) .
$$

Proof. Assume that $A$ solves the Cauchy problem (3.1) and set $D:=\partial_{\xi}^{-2} \partial_{\eta}^{2} A$. By Proposition 1, since the initial data satisfies $A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)$ and $\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)$ with $s \geq 0$, the KP-II equation has a solution

$$
\begin{equation*}
A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+6}\right) \cap C^{2}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right) \tag{3.3}
\end{equation*}
$$

such that $\partial_{\xi}^{-1} \partial_{\eta} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+8}\right) \cap C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+5}\right)$. Taking $\partial_{\eta}^{2}(\cdot)$ of the KP-II equation yields

$$
\partial_{\xi}^{2} \partial_{\tau} D+\partial_{\xi} \partial_{\eta}^{2}\left(A^{2}\right)+\partial_{\xi}^{5} D+\partial_{\xi} \partial_{\eta}^{2} D=0
$$

Setting $\tilde{D}:=D+A^{2}$ and taking $\partial_{\xi}^{-2}(\cdot)$ yields the evolution equation

$$
\begin{equation*}
\partial_{\tau} \tilde{D}+\partial_{\xi}^{3} \tilde{D}+\partial_{\xi}^{-1} \partial_{\eta}^{2} \tilde{D}=\partial_{\tau}\left(A^{2}\right)+\partial_{\xi}^{3}\left(A^{2}\right) \tag{3.4}
\end{equation*}
$$

Let us define $\Omega:=\partial_{\xi}^{-1} \partial_{\eta}^{2}+\partial_{\xi}^{3}$ and $S(\tau):=e^{\tau \Omega}$. Since $\Omega$ is skew-adjoint, the evolution operator $S(\tau)$ is unitary in $L^{2}\left(\mathbb{R}^{2}\right)$. Using Duhamel's principle, we can write the evolution equation (3.4) in the integral form:

$$
\tilde{D}(\tau)=S(\tau) \tilde{D}_{0}+\int_{0}^{\tau} S(\tau-s)\left[\partial_{s}\left(A^{2}\right)+\partial_{\xi}^{3}\left(A^{2}\right)\right](s) d s
$$

where $\tilde{D}_{0}=\partial_{\xi}^{-2} \partial_{\eta}^{2} A_{0}+A_{0}^{2}$. Expressing back $D=\tilde{D}-A$ gives us an integral equation for $D(\tau)$ of the form

$$
\begin{equation*}
D(\tau)=S(\tau) \tilde{D}_{0}-A(\tau)^{2}+\int_{0}^{\tau} S(\tau-s)\left[\partial_{s}\left(A^{2}\right)+\partial_{\xi}^{3}\left(A^{2}\right)\right](s) d s \tag{3.5}
\end{equation*}
$$

Since $\tilde{D}_{0} \in H^{s+9}\left(\mathbb{R}^{2}\right)$ and $S(\tau)$ is unitary in $L^{2}\left(\mathbb{R}^{2}\right)$, the local solution (3.3) yields $D \in$ $C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+6}\right)$.

Taking the time derivative of the integral equation (3.5), using

$$
\frac{d}{d \tau} S(\tau-s)=-\frac{d}{d s} S(\tau-s)
$$

and integrating by parts, we obtain

$$
\begin{aligned}
\partial_{\tau} D(\tau)= & S(\tau)\left[\Omega \tilde{D}_{0}+2 A_{0} \partial_{\tau} A_{0}+\partial_{\xi}^{3}\left(A_{0}^{2}\right)\right]-2 A(\tau) \partial_{\tau} A(\tau) \\
& +\int_{0}^{\tau} S(\tau-s) \partial_{s}\left[\partial_{s}\left(A^{2}\right)+\partial_{\xi}^{3}\left(A^{2}\right)\right](s) d s
\end{aligned}
$$

Since $\Omega \tilde{D}_{0} \in H^{s+3}\left(\mathbb{R}^{2}\right)$, then the solution (3.3) satisfies $\partial_{\tau} D \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right)$, which gives $\partial_{\xi}^{-2} \partial_{\eta}^{2} A$ $\in C^{1}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right)$.

It remains to control $\partial_{\tau}^{3} A$ and $\partial_{\xi}^{-1} \partial_{\eta} \partial_{\tau}^{2} A$, which is achieved by computing the time derivatives of the KP-II equation:

$$
\begin{aligned}
& \partial_{\tau}^{2} A=-\left(2 \partial_{\xi}\left(A \partial_{\tau} A\right)+\partial_{\xi}^{3} \partial_{\tau} A+\partial_{\xi}^{-1} \partial_{\eta}^{2} \partial_{\tau} A\right) \\
& \partial_{\tau}^{3} A=-\left(2 \partial_{\xi}\left(\left(\partial_{\tau} A\right)^{2}+A \partial_{\tau}^{2} A\right)+\partial_{\xi}^{3} \partial_{\tau}^{2} A+\partial_{\xi}^{-1} \partial_{\eta}^{2} \partial_{\tau}^{2} A\right)
\end{aligned}
$$

It follows from (3.3) that all but the last term in $\partial_{\tau}^{3} A$ are in $C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\right)$. By using the expression for $\partial_{\tau}^{2} A$, we check that

$$
\begin{equation*}
\partial_{\xi}^{-1} \partial_{\tau}^{2} A=-\left(2 A \partial_{\tau} A+\partial_{\xi}^{2} \partial_{\tau} A+\partial_{\tau} D\right), \tag{3.6}
\end{equation*}
$$

so that $\partial_{\xi}^{-1} \partial_{\tau}^{2} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+3}\right)$, which yields $A \in C^{3}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\right)$ and $\partial_{\xi}^{-1} \partial_{\eta} A \in$ $C^{2}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+2}\right)$.

Next we derive a useful bound on the $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm of a function expressed in terms of the slowly varying solution of the KP-II equation defined in $H^{s}\left(\mathbb{R}^{2}\right)$. A similar result for one-dimensional chains was obtained in [9] (see also [31] for earlier work).

Proposition 2. [9] Let $u_{j}=U(\varepsilon j)$, where $U \in H^{1}(\mathbb{R})$. There is a constant $C>0$ such that for every $\varepsilon \in(0,1]$ we have

$$
\begin{equation*}
\|u\|_{\ell^{2}(\mathbb{Z})} \leq C \varepsilon^{-\frac{1}{2}}\|U\|_{H^{1}(\mathbb{R})}, \quad \forall U \in H^{1}(\mathbb{R}) \tag{3.7}
\end{equation*}
$$

The following lemma generalizes Proposition 2 for two-dimensional square lattices.

Lemma 2. Let $u_{j, k}=U\left(\varepsilon j, \varepsilon^{2} k\right)$, where $U \in H^{s}\left(\mathbb{R}^{2}\right)$ with fixed $s>1$. There is a constant $C_{s}>0$ that depends on $s$ such that for every $\varepsilon \in(0,1]$ we have

$$
\begin{equation*}
\|u\|_{\ell^{2}\left(\mathbb{Z}^{2}\right)} \leq C_{s} \varepsilon^{-\frac{3}{2}}\|U\|_{H^{s}\left(\mathbb{R}^{2}\right)}, \quad \forall U \in H^{s}\left(\mathbb{R}^{2}\right) \tag{3.8}
\end{equation*}
$$

Proof. We use the discrete Fourier transform defined by

$$
\hat{u}(\theta, \phi)=\sum_{(j, k) \in \mathbb{Z}^{2}} u_{j, k} e^{-i(j \theta+k \phi)}
$$

with the inverse transform given by

$$
\begin{equation*}
u_{j, k}=\frac{1}{(2 \pi)^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \hat{u}(\theta, \phi) e^{i(j \theta+k \phi)} d \theta d \phi \tag{3.9}
\end{equation*}
$$

Since $U \in H^{s}\left(\mathbb{R}^{2}\right)$ and $s>1$, the Fourier transform of $U$ denoted by $\hat{U}$ can be defined through the standard formula. We represent

$$
\begin{align*}
u_{j, k} & =U\left(\varepsilon j, \varepsilon^{2} k\right)=\frac{1}{(2 \pi)^{2}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \hat{U}(\tilde{p}, \tilde{q}) e^{i\left(\varepsilon j \tilde{p}+\varepsilon^{2} k \tilde{q}\right)} d \tilde{p} d \tilde{q} \\
& =\frac{1}{(2 \pi)^{2} \varepsilon^{3}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \hat{U}\left(\frac{p}{\varepsilon}, \frac{q}{\varepsilon^{2}}\right) e^{i(j p+k q)} d p d q \\
& =\frac{1}{(2 \pi)^{2} \varepsilon^{3}} \sum_{(n, m) \in \mathbb{Z}^{2}} \int_{(2 n-1) \pi}^{(2 n+1) \pi} \int_{(2 m+1) \pi}^{\pi} \hat{U}\left(\frac{p}{\varepsilon}, \frac{q}{\varepsilon^{2}}\right) e^{i(j p+k q)} d p d q  \tag{3.10}\\
& =\frac{1}{(2 \pi)^{2} \varepsilon^{3}} \sum_{(n, m) \in \mathbb{Z}^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \hat{U}\left(\frac{\theta+2 \pi m}{\varepsilon}, \frac{\phi+2 \pi n}{\varepsilon^{2}}\right) e^{i(j \theta+k \phi)} d \theta d \phi
\end{align*}
$$

For any finite subset $\Lambda \subset \mathbb{Z}^{2}$, we have

$$
\sum_{(n, m) \in \Lambda} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi}\left|\hat{U}\left(\frac{\theta+2 \pi m}{\varepsilon}, \frac{\phi+2 \pi n}{\varepsilon^{2}}\right)\right| d \theta d \phi \leq \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\left|\hat{U}\left(\frac{p}{\varepsilon}, \frac{q}{\varepsilon^{2}}\right)\right| d p d q
$$

hence

$$
\sum_{(n, m) \in \mathbb{Z}^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi}\left|\hat{U}\left(\frac{\theta+2 \pi m}{\varepsilon}, \frac{\phi+2 \pi n}{\varepsilon^{2}}\right)\right| d \theta d \phi \leq\|\hat{U}\|_{L^{1}\left(\mathbb{R}^{2}\right)} \varepsilon^{3},
$$

where $\|\hat{U}\|_{L^{1}\left(\mathbb{R}^{2}\right)}<\infty$ if $U \in H^{s}\left(\mathbb{R}^{2}\right)$ with $s>1$. Then, we can interchange summation and integration in (3.10) by the Fubini-Tonelli theorem. Comparing (3.9) and (3.10) yields

$$
\hat{u}(\theta, \phi)=\frac{1}{\varepsilon^{3}} \sum_{(n, m) \in \mathbb{Z}^{2}} \hat{U}\left(\frac{\theta+2 \pi m}{\varepsilon}, \frac{\phi+2 \pi n}{\varepsilon^{2}}\right) .
$$

Parseval's identity yields

$$
\|u\|_{\ell^{2}\left(\mathbb{Z}^{2}\right)}^{2}=\frac{1}{(2 \pi)^{2} \varepsilon^{6}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi}\left|\sum_{(n, m) \in \mathbb{Z}^{2}} \hat{U}\left(\frac{\theta+2 \pi m}{\varepsilon}, \frac{\phi+2 \pi n}{\varepsilon^{2}}\right)\right|^{2} d \theta d \phi
$$

$$
\begin{aligned}
& \leq \frac{1}{(2 \pi)^{2} \varepsilon^{6}} \sum_{\substack{\left(n_{1}, m_{1}\right) \in \mathbb{Z}^{2} \\
\left(n_{2}, m_{2}\right) \in \mathbb{Z}^{2}}} \int^{\pi} \int_{-\pi}^{\pi}\left|\hat{U}\left(\frac{\theta+2 \pi m_{1}}{\varepsilon}, \frac{\phi+2 \pi n_{1}}{\varepsilon^{2}}\right)\right| \\
& \times\left|\hat{U}\left(\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right)\right| d \theta d \phi .
\end{aligned}
$$

Denote $\langle x, y\rangle_{2}=\sqrt{1+x^{2}+y^{2}}$. Inserting the weights $\left\langle\frac{\pi m_{1}}{\varepsilon}, \frac{\pi n_{1}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s}$ and $\left\langle\frac{\pi m_{2}}{\varepsilon}, \frac{\pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s}$, then applying Young's inequality, $a b \leq \frac{1}{2} a^{2}+\frac{1}{2} b^{2}$, yields

$$
\begin{aligned}
\|u\|_{\ell^{2}\left(\mathbb{Z}^{2}\right)}^{2} \leq & \frac{1}{(2 \pi)^{2} \varepsilon^{6}} \sum_{\substack{\left(n_{1}, m_{1}\right) \in \mathbb{Z}^{2} \\
\left(n_{2}, m_{2}\right) \in \mathbb{Z}^{2}}}\left\langle\frac{\pi m_{1}}{\varepsilon}, \frac{\pi n_{1}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s}\left\langle\frac{\pi m_{2}}{\varepsilon}, \frac{\pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s} \\
& \times\left(\int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{1}{2}\left\langle\frac{\pi m_{1}}{\varepsilon}, \frac{\pi n_{1}}{\varepsilon^{2}}\right\rangle_{2}^{4 s}\left|\hat{U}\left(\frac{\theta+2 \pi m_{1}}{\varepsilon}, \frac{\phi+2 \pi n_{1}}{\varepsilon^{2}}\right)\right|^{2} d \theta d \phi\right. \\
& \left.+\int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \frac{1}{2}\left\langle\frac{\pi m_{2}}{\varepsilon}, \frac{\pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{4 s}\left|\hat{U}\left(\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right)\right|^{2} d \theta d \phi\right)
\end{aligned}
$$

Hence, by symmetry of coefficients, we obtain:

$$
\begin{aligned}
\|u\|_{\ell^{2}\left(\mathbb{Z}^{2}\right)}^{2} \leq \frac{1}{(2 \pi)^{2} \varepsilon^{6}} & \left(\sum_{\left(n_{1}, m_{1}\right) \in \mathbb{Z}^{2}}\left\langle\frac{\pi m_{1}}{\varepsilon}, \frac{\pi n_{1}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s}\right) \\
& \times\left(\sum_{\left(n_{2}, m_{2}\right) \in \mathbb{Z}^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi}\left\langle\frac{\pi m_{2}}{\varepsilon}, \frac{\pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{2 s}\left|\hat{U}\left(\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right)\right|^{2} d \theta d \phi\right) .
\end{aligned}
$$

When $\varepsilon \in(0,1]$ the double series in first term in $\|u\|_{\ell^{2}(\mathbb{Z})}^{2}$ converges for $s>1$ by the integral test, hence $\exists C_{s}>0$ so that

$$
\sum_{\left(n_{1}, m_{1}\right) \in \mathbb{Z}^{2}}\left\langle\frac{\pi m_{1}}{\varepsilon}, \frac{\pi n_{1}}{\varepsilon^{2}}\right\rangle_{2}^{-2 s}<C_{s}^{2}
$$

The second term in $\|u\|_{\ell^{2}(\mathbb{Z})}^{2}$ is related to the $H^{s}$ norm of $U$ given by,

$$
\begin{aligned}
\|U\|_{H^{s}}^{2} & =\frac{1}{(2 \pi)^{2}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty}\langle\tilde{p}, \tilde{q}\rangle_{2}^{2 s}|\hat{U}(\tilde{p}, \tilde{q})|^{2} d \tilde{p} d \tilde{q} \\
& =\frac{1}{(2 \pi)^{2} \varepsilon^{3}} \sum_{\left(n_{2}, m_{2}\right) \in \mathbb{Z}^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi}\left\langle\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{2 s} \\
& \times\left|\hat{U}\left(\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right)\right|^{2} d \theta d \phi
\end{aligned}
$$

Since

$$
\left\langle\frac{\pi m_{2}}{\varepsilon}, \frac{\pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{2 s} \leq\left\langle\frac{\theta+2 \pi m_{2}}{\varepsilon}, \frac{\phi+2 \pi n_{2}}{\varepsilon^{2}}\right\rangle_{2}^{2 s}, \quad \forall \theta, \phi \in[-\pi, \pi],
$$

the second term in $\|u\|_{\ell^{2}(\mathbb{Z})}^{2}$ is bounded above by $(2 \pi)^{2} \varepsilon^{3}\|U\|_{H^{s}}^{2}$. Hence, we obtain $\|u\|_{\ell^{2}\left(\mathbb{Z}^{2}\right)}^{2} \leq \varepsilon^{-3} C_{s}^{2}\|U\|_{H^{s}}^{2}$ which yields (3.8).

## 4. Proof of Theorem 1

Here, we use the results of Lemmas 1 and 2 in order to prove Theorem 1. We start by writing equations of motions in terms of the strain variables (2.6):

$$
\begin{align*}
\dot{u}_{j, k}^{(1)}= & w_{j+1, k}-w_{j, k}, \\
\dot{u}_{j, k}^{(2)}= & w_{j, k+1}-w_{j, k}, \\
\dot{v}_{j, k}^{(1)}= & z_{j+1, k}-z_{j, k}, \\
\dot{v}_{j, k}^{(2)}= & z_{j, k+1}-z_{j, k}, \\
\dot{w}_{j, k}= & c_{1}^{2}\left(u_{j, k}^{(1)}-u_{j-1, k}^{(1)}\right)+c_{2}^{2}\left(u_{j, k}^{(2)}-u_{j, k-1}^{(2)}\right) \\
& +\alpha_{1}\left[\left(u_{j, k}^{(1)}\right)^{2}-\left(u_{j-1, k}^{(1)}\right)^{2}\right] \\
& +\alpha_{2}\left[u_{j, k}^{(2)} v_{j, k}^{(2)}-u_{j, k-1}^{(2)} v_{j, k-1}^{(2)}+\frac{1}{2}\left(v_{j, k}^{(1)}\right)^{2}-\frac{1}{2}\left(v_{j-1, k}^{(1)}\right)^{2}\right] \\
\dot{z}_{j, k}= & c_{1}^{2}\left(v_{j, k}^{(2)}-v_{j, k-1}^{(2)}\right)+c_{2}^{2}\left(v_{j, k}^{(1)}-v_{j-1, k}^{(1)}\right), \\
& +\alpha_{1}\left[\left(v_{j, k}^{(2)}\right)^{2}-\left(v_{j, k-1}^{(2)}\right)^{2}\right] \\
& +\alpha_{2}\left[u_{j, k}^{(1)} v_{j, k}^{(1)}-u_{j-1, k}^{(1)} v_{j-1, k}^{(1)}+\frac{1}{2}\left(u_{j, k}^{(2)}\right)^{2}-\frac{1}{2}\left(u_{j, k-1}^{(2)}\right)^{2}\right], \tag{4.1}
\end{align*}
$$

where $w_{j, k}:=\dot{x}_{j, k}, z_{j, k}:=\dot{y}_{j, k}$, and $(j, k) \in \mathbb{Z}^{2}$. The justification procedure is divided into the following four steps.

### 4.1. Step 1. Decomposition

Let us use the following decomposition,

$$
\begin{align*}
u_{j, k}^{(1)} & =\varepsilon^{2} A(\xi, \eta, \tau)+\varepsilon^{2} U_{j, k}^{(1)} \\
u_{j, k}^{(2)} & =\varepsilon^{2} B_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} U_{j, k}^{(2)} \\
v_{j, k}^{(1)} & =\varepsilon^{2} V_{j, k}^{(1)}  \tag{4.2}\\
v_{j, k}^{(2)} & =\varepsilon^{2} V_{j, k}^{(2)} \\
w_{j, k} & =\varepsilon^{2} W_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} W_{j, k} \\
z_{j, k} & =\varepsilon^{2} Z_{j, k}
\end{align*}
$$

where $\xi=\varepsilon\left(j-c_{1} t\right), \eta=\varepsilon^{2} k$, and $\tau=\varepsilon^{3} t$. The leading-order function $A$ is defined as a suitable solution to the KP-II equation (2.9), whereas the $\varepsilon$-dependent functions $B_{\varepsilon}$ and $W_{\varepsilon}$ are introduced to eliminate the lower-order terms in $\varepsilon$ arising from time derivatives and finite differences of $A$ in the first and second equations of system (4.1).

We denote the error terms of the formal power $\varepsilon^{5}$ by $\mathcal{O}\left(\varepsilon^{5}\right)$ and define $W_{\varepsilon}$ and $U_{\varepsilon}$ from the following equations:

$$
\begin{equation*}
W_{\varepsilon}(\xi+\varepsilon, \eta)-W_{\varepsilon}(\xi, \eta)=-\varepsilon c_{1} \partial_{\xi} A(\xi, \eta)+\varepsilon^{3} \partial_{\tau} A(\xi, \eta)+\mathcal{O}\left(\varepsilon^{5}\right) \tag{4.3}
\end{equation*}
$$

and

$$
\begin{equation*}
W_{\varepsilon}\left(\xi, \eta+\varepsilon^{2}\right)-W_{\varepsilon}(\xi, \eta)=-\varepsilon c_{1} \partial_{\xi} B_{\varepsilon}(\xi, \eta)+\varepsilon^{3} \partial_{\tau} B_{\varepsilon}(\xi, \eta)+\mathcal{O}\left(\varepsilon^{5}\right) \tag{4.4}
\end{equation*}
$$

where the time dependence is dropped from the list of arguments.
We look for an approximate solution to (4.3) in the form:

$$
\begin{equation*}
W_{\varepsilon}=W^{(0)}+\varepsilon W^{(1)}+\varepsilon^{2} W^{(2)}+\varepsilon^{3} W^{(3)} \tag{4.5}
\end{equation*}
$$

where the functions $W^{(j)}$ depend on $(\xi, \eta)$ and decay to zero at infinity. Plugging (4.5) into (4.3) and expanding each $W^{(j)}$ in Taylor series, we get

$$
\begin{aligned}
\varepsilon \partial_{\xi} W^{(0)}+ & \frac{1}{2} \varepsilon^{2} \partial_{\xi}^{2} W^{(0)}+\frac{1}{6} \varepsilon^{3} \partial_{\xi}^{3} W^{(0)}+\frac{1}{24} \varepsilon^{4} \partial_{\xi}^{4} W^{(0)} \\
& +\varepsilon^{2} \partial_{\xi} W^{(1)}+\frac{1}{2} \varepsilon^{3} \partial_{\xi}^{2} W^{(1)}+\frac{1}{6} \varepsilon^{4} \partial_{\xi}^{3} W^{(1)}+\varepsilon^{3} \partial_{\xi} W^{(2)}+\frac{1}{2} \varepsilon^{4} \partial_{\xi}^{2} W^{(2)} \\
& +\varepsilon^{4} \partial_{\xi} W^{(3)}=-\varepsilon c_{1} \partial_{\xi} A+\varepsilon^{3} \partial_{\tau} A+\mathcal{O}\left(\varepsilon^{5}\right) .
\end{aligned}
$$

Grouping terms by their orders in powers of $\varepsilon$ yields a sequence of equations with their relevant solutions:

$$
\begin{align*}
\mathcal{O}(\varepsilon): & \partial_{\xi} W^{(0)}=-c_{1} \partial_{\xi} A \\
\Longrightarrow & W^{(0)}=-c_{1} A \\
\mathcal{O}\left(\varepsilon^{2}\right): & \frac{1}{2} \partial_{\xi}^{2} W^{(0)}+\partial_{\xi} W^{(1)}=0 \\
\Longrightarrow & W^{(1)}=\frac{c_{1}}{2} \partial_{\xi} A \\
\mathcal{O}\left(\varepsilon^{3}\right): & \frac{1}{6} \partial_{\xi}^{3} W^{(0)}+\frac{1}{2} \partial_{\xi}^{2} W^{(1)}+\partial_{\xi} W^{(2)}=\partial_{\tau} A  \tag{4.6}\\
\Longrightarrow & W^{(2)}=\partial_{\xi}^{-1} \partial_{\tau} A-\frac{c_{1}}{12} \partial_{\xi}^{2} A \\
\mathcal{O}\left(\varepsilon^{4}\right): & \frac{1}{24} \partial_{\xi}^{4} W^{(0)}+\frac{1}{6} \partial_{\xi}^{3} W^{(1)}+\frac{1}{2} \partial_{\xi}^{2} W^{(2)}+\partial_{\xi} W^{(3)}=0 \\
\Longrightarrow & W^{(3)}=-\frac{1}{2} \partial_{\tau} A .
\end{align*}
$$

With the choice in (4.6), this construction ensures that equation (4.3) is satisfied up to and including the order of $\mathcal{O}\left(\varepsilon^{4}\right)$. Substituting (4.6) into (4.5) yields

$$
\begin{equation*}
W_{\varepsilon}=-c_{1} A+\varepsilon\left(\frac{c_{1}}{2} \partial_{\xi} A\right)+\varepsilon^{2}\left(\partial_{\xi}^{-1} \partial_{\tau} A-\frac{c_{1}}{12} \partial_{\xi}^{2} A\right)-\varepsilon^{3}\left(\frac{1}{2} \partial_{\tau} A\right) \tag{4.7}
\end{equation*}
$$

Similarly, we look for an approximate solution to (4.4) in the form:

$$
\begin{equation*}
B_{\varepsilon}=\varepsilon B^{(1)}+\varepsilon^{2} B^{(2)}+\varepsilon^{3} B^{(3)}, \tag{4.8}
\end{equation*}
$$

where the functions $B^{(j)}$ depend on $(\xi, \eta)$ and decay to zero at infinity. Plugging (4.5) and (4.8) into (4.4) and expanding each $W^{(j)}$ in Taylor series, we get

$$
\begin{align*}
& \varepsilon^{2}\left(-c_{1} \partial_{\xi} B^{(1)}\right)+\varepsilon^{3}\left(-c_{1} \partial_{\xi} B^{(2)}\right)+\varepsilon^{4}\left(-c_{1} \partial_{\xi} B^{(3)}+\partial_{\tau} B^{(1)}\right) \\
& \quad=\varepsilon^{2} \partial_{\eta} W^{(0)}+\varepsilon^{3} \partial_{\eta} W^{(1)}+\varepsilon^{4}\left(\partial_{\eta} W^{(2)}+\frac{1}{2} \partial_{\eta}^{2} W^{(0)}\right)+\mathcal{O}\left(\varepsilon^{5}\right) \tag{4.9}
\end{align*}
$$

Grouping terms by their orders in powers of $\varepsilon$ and using the values for $W_{\varepsilon}$ found in (4.6), we obtain a sequence of equations with their relevant solutions:

$$
\begin{align*}
& \mathcal{O}\left(\varepsilon^{2}\right): \quad-c_{1} \partial_{\xi} B^{(1)}=-c_{1} \partial_{\eta} A \\
& \quad \Longrightarrow \quad B^{(1)}=\partial_{\xi}^{-1} \partial_{\eta} A \\
& \mathcal{O}\left(\varepsilon^{3}\right): \quad-c_{1} \partial_{\xi} B^{(2)}=\frac{c_{1}}{2} \partial_{\xi} \partial_{\eta} A \\
& \quad \Longrightarrow \quad B^{(2)}=-\frac{1}{2} \partial_{\eta} A  \tag{4.10}\\
& \mathcal{O}\left(\varepsilon^{4}\right): \quad-c_{1} \partial_{\xi} B^{(3)}+\partial_{\tau} B^{(1)}=\partial_{\xi}^{-1} \partial_{\eta} \partial_{\tau} A-\frac{c_{1}}{12} \partial_{\xi}^{2} \partial_{\eta} A-\frac{c_{1}}{2} \partial_{\eta}^{2} A \\
& \quad \Longrightarrow \quad B^{(3)}=\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{12} \partial_{\xi} \partial_{\eta} A
\end{align*}
$$

Substituting (4.10) into (4.8) yields

$$
\begin{equation*}
B_{\varepsilon}=\varepsilon \partial_{\xi}^{-1} \partial_{\eta} A-\varepsilon^{2}\left(\frac{1}{2} \partial_{\eta} A\right)+\varepsilon^{3}\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{12} \partial_{\xi} \partial_{\eta} A\right) \tag{4.11}
\end{equation*}
$$

Substituting decomposition (4.2) into the first and second equations of system (4.1) yield equations

$$
\begin{gather*}
\dot{U}_{j, k}^{(1)}=W_{j+1, k}-W_{j, k}+\operatorname{Res}_{j, k}^{U_{j, k}^{(1)}}, \\
\dot{U}_{j, k}^{(2)}=W_{j, k+1}-W_{j, k}+\operatorname{Res}_{j, k}^{U^{(2)}}, \tag{4.12}
\end{gather*}
$$

where

$$
\begin{aligned}
& \operatorname{Res}_{j, k}^{U_{j(1)}^{(1)}}:=c_{1} \varepsilon \partial_{\xi} A-\varepsilon^{3} \partial_{\tau} A+W_{\varepsilon}(\xi+\varepsilon, \eta)-W_{\varepsilon}(\xi, \eta), \\
& \operatorname{Res}_{j, k}^{U^{(2)}}:=c_{1} \varepsilon \partial_{\xi} B_{\varepsilon}-\varepsilon^{3} \partial_{\tau} B_{\varepsilon}+W_{\varepsilon}\left(\xi, \eta+\varepsilon^{2}\right)-W_{\varepsilon}(\xi, \eta) .
\end{aligned}
$$

If expansions (4.7) and (4.11) are used, the residual terms have the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$. The third and fourth equations of system (4.1) have not been changed:

$$
\begin{gather*}
\dot{V}_{j, k}^{(1)}=Z_{j+1, k}-Z_{j, k}, \\
\dot{V}_{j, k}^{(2)}=Z_{j, k+1}-Z_{j, k} . \tag{4.13}
\end{gather*}
$$

Finally, the last two equations of system (4.1) can be rewritten explicitly as

$$
\begin{align*}
\dot{W}_{j, k}= & c_{1}^{2}\left[U_{j, k}^{(1)}-U_{j-1, k}^{(1)}\right]+c_{2}^{2}\left[U_{j, k}^{(2)}-U_{j, k-1}^{(2)}\right] \\
& +\alpha_{1} \varepsilon^{2}\left[2 A U_{j, k}^{(1)}-2 A(\xi-\varepsilon, \eta) U_{j-1, k}^{(1)}+\left(U_{j, k}^{(1)}\right)^{2}-\left(U_{j-1, k}^{(1)}\right)^{2}\right] \\
& +\alpha_{2} \varepsilon^{2}\left[B_{\varepsilon}(\xi, \eta) V_{j, k}^{(2)}-B_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right) V_{j, k-1}^{(2)}+U_{j, k}^{(2)} V_{j, k}^{(2)}-U_{j, k-1}^{(2)} V_{j, k-1}^{(2)}\right] \\
& +\alpha_{2} \varepsilon^{2}\left[\frac{1}{2}\left(V_{j, k}^{(1)}\right)^{2}-\frac{1}{2}\left(V_{j-1, k}^{(1)}\right)^{2}\right]+\operatorname{Res}_{j, k}^{W}  \tag{4.14}\\
\dot{Z}_{j, k}= & c_{2}^{2}\left[V_{j, k}^{(1)}-V_{j-1, k}^{(1)}\right]+c_{1}^{2}\left[V_{j, k}^{(2)}-V_{j, k-1}^{(2)}\right] \\
& +\alpha_{2} \varepsilon^{2}\left[B_{\varepsilon}(\xi, \eta) U_{j, k}^{(2)}-B_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right) U_{j, k-1}^{(2)}+\frac{1}{2}\left(U_{j, k}^{(2)}\right)^{2}-\frac{1}{2}\left(U_{j, k-1}^{(2)}\right)^{2}\right] \\
& +\alpha_{2} \varepsilon^{2}\left[A(\xi, \eta) V_{j, k}^{(1)}-A(\xi-\varepsilon, \eta) V_{j-1, k}^{(1)}+V_{j, k}^{(1)} U_{j, k}^{(1)}-V_{j-1, k}^{(1)} U_{j-1, k}^{(1)}\right] \\
& +\alpha_{1} \varepsilon^{2}\left[\left(V_{j, k}^{(2)}\right)^{2}-\left(V_{j, k-1}^{(2)}\right)^{2}\right]+\operatorname{Res}_{j, k}^{Z}
\end{align*}
$$

where

$$
\begin{aligned}
\operatorname{Res}_{j, k}^{W}:= & c_{1} \varepsilon \partial_{\xi} W_{\varepsilon}-\varepsilon^{3} \partial_{\tau} W_{\varepsilon}+c_{1}^{2}[A(\xi, \eta)-A(\xi-\varepsilon, \eta)] \\
& +c_{2}^{2}\left[B_{\varepsilon}(\xi, \eta)-B_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right)\right]+\alpha_{1} \varepsilon^{2}\left[A(\xi, \eta)^{2}-A(\xi-\varepsilon, \eta)^{2}\right], \\
\operatorname{Res}_{j, k}^{Z}:= & \frac{\alpha_{2} \varepsilon^{2}}{2}\left[B_{\varepsilon}(\xi, \eta)^{2}-B_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right)^{2}\right] .
\end{aligned}
$$

Expanding each term in $R e s_{j, k}^{W}$ by using expansions (4.7) and (4.11) yields the following formal expansion

$$
\begin{aligned}
\operatorname{Res} j_{j, k}^{W}= & \varepsilon^{3}\left[2 c_{1} \partial_{\tau} A+\frac{c_{1}^{2}}{12} \partial_{\xi}^{3} A+c_{2}^{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\alpha_{1} \partial_{\xi}\left(A^{2}\right)\right] \\
& -\varepsilon^{4}\left[c_{1} \partial_{\xi} \partial_{\tau} A+\frac{c_{1}^{2}}{24} \partial_{\xi}^{4} A+\frac{c_{2}^{2}}{2} \partial_{\eta}^{2} A+\frac{\alpha_{1}}{2} \partial_{\xi}^{2}\left(A^{2}\right)\right]+\mathcal{O}\left(\varepsilon^{5}\right)
\end{aligned}
$$

If the function $A$ is a solution of the KP-II equation (2.9), the residual term Res ${ }^{W}$ has the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$. It is also clear from expansion (4.11) that Res ${ }^{Z}$ has the formal order of $\mathcal{O}\left(\varepsilon^{6}\right)$.

### 4.2. Step 2. Residual terms

The residual terms are handled by using Taylor's theorem. If $A$ is defined in Sobolev space $H^{s}\left(\mathbb{R}^{2}\right)$ with sufficiently large $s$, then we can estimate the residual terms in the $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm by an application of Lemma 2. Since all residual terms have the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$, we can obtain the bound of $\mathcal{O}\left(\varepsilon^{\frac{7}{2}}\right)$ on the residual terms in the $\ell^{2}(\mathbb{Z})$ norm.

The following lemma gives us estimates of the $\ell^{2}$-norm for the residual terms in equations (4.12) and (4.14). No residual terms appear in equations (4.13).

Lemma 3. Let $A \in C^{0}\left(\mathbb{R}, H^{s}\right)$ be a solution to the KP-II equation (2.9) with $s \geq 9$. There is a positive constant $C$ that depend on $A$ such that for all $\varepsilon \in(0,1]$, we have

$$
\begin{equation*}
\left\|\operatorname{Res}_{j, k}^{U^{(1)}}\right\|_{\ell^{2}}+\left\|\operatorname{Res}_{j, k}^{U^{(2)}}\right\|_{\ell^{2}}+\left\|\operatorname{Res}_{j, k}^{W}\right\|_{\ell^{2}}+\left\|\operatorname{Res}_{j, k}^{Z}\right\|_{\ell^{2}} \leq C \varepsilon^{\frac{7}{2}} . \tag{4.15}
\end{equation*}
$$

Proof. By construction, all terms in Res $s_{j, k}^{U^{(1)}}$ below the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ vanish. From the Taylor's theorem for $W_{\varepsilon}(\xi+\varepsilon, \eta)-W_{\varepsilon}(\xi, \eta)$, the nonzero terms at $\mathcal{O}\left(\varepsilon^{5}\right)$ are given by the integrals:

$$
\varepsilon^{5} \int_{0}^{1} \partial_{\xi}^{5-l} W^{(l)}\left(\varepsilon(j+r), \varepsilon^{2} k\right) \frac{(1-r)^{5-l-1}}{(5-l-1)!} d r, \quad 0 \leq l \leq 3 .
$$

In view of corrections for $W^{(l)}$ in (4.7), the error is given by a linear combination of the following two terms:

$$
\varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi}^{5} A\left(\varepsilon(j+r), \varepsilon^{2} k\right)\right|, \quad \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi}^{2} \partial_{\tau} A\left(\varepsilon(j+r), \varepsilon^{2} k\right)\right| .
$$

Using Lemma 2, there is a constant $C_{s}>0$ such that the $\ell^{2}$ norm of the residual term Res ${ }^{U^{(1)}}$ is bounded by

$$
\left\|\operatorname{Res}^{U^{(1)}}\right\|_{\ell^{2}} \leq C_{s} \varepsilon^{\frac{7}{2}}\left(\|A\|_{H^{s+5}}+\left\|\partial_{\tau} A\right\|_{H^{s+2}}\right)
$$

for $s>1$.

Similarly, all terms in $\operatorname{Res}_{j, k}^{U^{(2)}}$ below the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ vanish. From the Taylor's theorem for $W_{\varepsilon}\left(\xi, \eta+\varepsilon^{2}\right)-W_{\varepsilon}(\xi, \eta)$ and the corrections for $W_{\varepsilon}$ and $U_{\varepsilon}$ given by (4.7) and (4.11), the error is given by a linear combination of the following six terms:

$$
\begin{aligned}
& \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right| \\
& \varepsilon^{6} \sup _{r \in[0,1]}\left|\partial_{\eta}^{3} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|, \\
& \varepsilon^{6} \sup _{r \in[0,1]}\left|\partial_{\xi}^{-1} \partial_{\eta}^{2} \partial_{\tau} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|,
\end{aligned}
$$

$$
\begin{array}{r}
\varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\eta} \partial_{\tau} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|, \\
\varepsilon^{6} \sup _{r \in[0,1]}\left|\partial_{\xi}^{2} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|, \\
\quad \varepsilon^{6}\left|\partial_{\xi} \partial_{\eta} \partial_{\tau} A\left(\varepsilon j, \varepsilon^{2} k\right)\right| .
\end{array}
$$

Using Lemma 2, there is a constant $C_{s}>0$ such that the $\ell^{2}$ norm of the residual term Res ${ }^{U^{(2)}}$ is bounded for $\varepsilon \in(0,1]$ by

$$
\left\|\operatorname{Res}^{U^{(2)}}\right\|_{\ell^{2}} \leq C_{s} \varepsilon^{\frac{7}{2}}\left(\|A\|_{H^{s+4}}+\left\|\partial_{\tau} A\right\|_{H^{s+2}}+\left\|\partial_{\xi}^{-1} \partial_{\eta} \partial_{\tau} A\right\|_{H^{s+1}}\right)
$$

for $s>1$.
If $A \in C^{0}\left(\mathbb{R}, H^{s}\right)$ is a solution to the KPII equation (2.9) with $s \geq 9$, all terms in Res $s_{j, k}^{W}$ below the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ vanish. Expanding all terms in $\operatorname{Res}_{j, k}^{W}$ shows that the error is given by a linear combination of the following eight terms:

$$
\begin{aligned}
& \varepsilon^{5}\left|\partial_{\xi}^{-1} \partial_{\tau}^{2} A\left(\varepsilon j, \varepsilon^{2} k\right)\right|, \quad \varepsilon^{5}\left|\partial_{\xi}^{2} \partial_{\tau} A\left(\varepsilon j, \varepsilon^{2} k\right)\right|, \quad \varepsilon^{6}\left|\partial_{\tau}^{2} A\left(\varepsilon j, \varepsilon^{2} k\right)\right|, \\
& \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi}^{5} A\left(\varepsilon(j+r), \varepsilon^{2} k\right)\right|, \quad \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi}^{3} A^{2}\left(\varepsilon(j+r), \varepsilon^{2} k\right)\right|, \\
& \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi}^{-1} \partial_{\eta}^{3} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|, \quad \varepsilon^{5} \sup _{r \in[0,1]}\left|\partial_{\xi} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|,
\end{aligned}
$$

and

$$
\varepsilon^{6} \sup _{r \in[0,1]}\left|\partial_{\eta}^{3} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|
$$

Using Lemma 2 and the relation (3.6) for $\partial_{\xi}^{-1} \partial_{\tau}^{2} A$, there is a constant $C_{s}>0$ such that the $\ell^{2}$ norm of the residual term Res ${ }^{W}$ is bounded for $\varepsilon \in(0,1]$ by

$$
\begin{gathered}
\left\|\operatorname{Res}^{W}\right\|_{\ell^{2}} \leq C_{s} \varepsilon^{\frac{7}{2}}\left(\left\|\partial_{\tau}^{2} A\right\|_{H^{s}}+\left\|\partial_{\tau} A\right\|_{H^{s+2}}+\left\|\partial_{\xi}^{-2} \partial_{\eta}^{2} \partial_{\tau} A\right\|_{H^{s}}+\|A\|_{H^{s+5}}+\left\|\partial_{\xi}^{-1} \partial_{\eta} A\right\|_{H^{s+2}}\right. \\
\left.+\|A\|_{H^{s}}\|A\|_{H^{s+3}}+\|A\|_{H^{s}}\left\|\partial_{\tau} A\right\|_{H^{s}}\right)
\end{gathered}
$$

for $s>1$.
The final residual term $R e s s_{j, k}^{Z}$ is estimated from the expansion (4.11). The error is given by

$$
\begin{aligned}
& \varepsilon^{6} \sup _{r \in[0,1]}\left[\left|\partial_{\xi}^{-1} \partial_{\eta} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|+\varepsilon\left|\partial_{\eta} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|\right. \\
& \left.\quad+\varepsilon^{2}\left|\partial_{\xi}^{-1} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|+\varepsilon^{2}\left|\partial_{\xi} \partial_{\eta} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|\right] \\
& \quad \times \sup _{r \in[0,1]}\left[\left|\partial_{\xi}^{-1} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|+\varepsilon\left|\partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|\right. \\
& \left.\quad+\varepsilon^{2}\left|\partial_{\xi}^{-1} \partial_{\eta}^{3} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|+\varepsilon^{2}\left|\partial_{\xi} \partial_{\eta}^{2} A\left(\varepsilon j, \varepsilon^{2}(k+r)\right)\right|\right]
\end{aligned}
$$

and is controlled in the $\ell^{2}$ norm by using the bound

$$
\left\|\operatorname{Res}^{Z}\right\|_{\ell^{2}} \leq C_{s} \varepsilon^{\frac{9}{2}}\left(\left\|\partial_{\xi}^{-1} \partial_{\eta} A\right\|_{H^{s+2}}^{2}+\|A\|_{H^{s+3}}^{2}\right)
$$

where $C_{s}>0, s>1$, and $\varepsilon \in(0,1]$.

Combining all four bounds together and using the fact that a solution $A \in C^{0}\left(\mathbb{R}, H^{s}\right)$ to the KP-II equation (2.9) with $s \geq 9$ enjoys the estimates of Lemma 1, we obtain the bound (4.15).

### 4.3. Step 3. Energy estimates

In order to control the growth of the approximation error from solutions to system (4.12), (4.13), and (4.14), we will introduce the following energy function,

$$
\begin{align*}
E(t)= & f r a c 12 \sum_{j, k \in \mathbb{Z}^{2}} W_{j, k}^{2}+Z_{j, k}^{2}+c_{1}^{2}\left(U_{j, k}^{(1)}\right)^{2}+c_{2}^{2}\left(U_{j, k}^{(2)}\right)^{2}+c_{1}^{2}\left(V_{j, k}^{(1)}\right)^{2}+c_{2}^{2}\left(V_{j, k}^{(2)}\right)^{2} \\
& +\alpha_{1} \varepsilon^{2}\left[2 A\left(U_{j, k}^{(1)}\right)^{2}+\frac{2}{3}\left(U_{j, k}^{(1)}\right)^{3}+\frac{2}{3}\left(V_{j, k}^{(2)}\right)^{3}\right]  \tag{4.16}\\
& +\alpha_{2} \varepsilon^{2}\left[A\left(V_{j, k}^{(1)}\right)^{2}+U_{j, k}^{(1)}\left(V_{j, k}^{(1)}\right)^{2}+\left(U_{j, k}^{(2)}\right)^{2} V_{j, k}^{(2)}+2 B_{\varepsilon} U_{j, k}^{(2)} V_{j, k}^{(2)}\right] .
\end{align*}
$$

The $\varepsilon$-dependent terms of $E(t)$ are chosen from the condition that the growth rate $E^{\prime}(t)$ along the solution of system (4.12), (4.13), and (4.14) does not contain terms of the formal orders $\mathcal{O}(\varepsilon)$ and $\mathcal{O}\left(\varepsilon^{2}\right)$ (see Lemma 5 below).

The following lemma establishes coercivity of the energy $E(t)$ with respect to the $\ell^{2}$ norm of the perturbations as long as the perturbations are not large in the $\ell^{2}$ norm.

Lemma 4. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\left(\mathbb{R}^{2}\right)\right)$ and $\partial_{\xi}^{-1} \partial_{\eta} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s-1}\left(\mathbb{R}^{2}\right)\right)$ with $s>3$ and assume that $E(t) \leq E_{0}$ for some $\varepsilon$-independent constant $E_{0}>0$ for every $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$. There exist some constants $\varepsilon_{0}>0$ and $K_{0}>0$ that depend on $A$ such that

$$
\begin{equation*}
\|W\|_{\ell^{2}}^{2}+\|Z\|_{\ell^{2}}^{2}+\left\|U^{(1)}\right\|_{\ell^{2}}^{2}+\left\|U^{(2)}\right\|_{\ell^{2}}^{2}+\left\|V^{(1)}\right\|_{\ell^{2}}^{2}+\left\|V^{(2)}\right\|_{\ell^{2}}^{2} \leq 2 K_{0} E(t), \tag{4.17}
\end{equation*}
$$

for each $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Proof. It follows from the decomposition (4.11) and Sobolev's embedding of $H^{s}\left(\mathbb{R}^{2}\right)$ into $L^{\infty}\left(\mathbb{R}^{2}\right)$ for $s>1$ that if $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\left(\mathbb{R}^{2}\right)\right)$ and $\partial_{\xi}^{-1} \partial_{\eta} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s-1}\left(\mathbb{R}^{2}\right)\right)$ with $s>3$, then there exists a constant $C_{0}>0$ that depends on $A$ such that

$$
\sup _{t \in\left[-\tau_{0}, \tau_{0}\right]}\left(\|A(\cdot, \tau)\|_{L^{\infty}\left(\mathbb{R}^{2}\right)}+\left\|U_{\varepsilon}(\cdot, \tau)\right\|_{L^{\infty}\left(\mathbb{R}^{2}\right)}\right) \leq C_{0}
$$

By using (4.16) and the Cauchy-Schwarz inequality for $U_{j, k}^{(2)} V_{j, k}^{(2)}$, we derive the following lower bound for $E(t)$ :

$$
\begin{aligned}
2 E(t) \geq & \|W\|_{\ell^{2}}^{2}+\|Z\|_{\ell^{2}}^{2} \\
& +\left(c_{1}^{2}-2 \alpha_{1} \varepsilon^{2} C_{0}-\frac{2}{3} \alpha_{1} \varepsilon^{2}\left\|U^{(1)}\right\| \ell_{\ell \infty}\right)\left\|U^{(1)}\right\|_{\ell^{2}}^{2} \\
& +\left(c_{2}^{2}-\alpha_{2} \varepsilon^{2} C_{0}-\alpha_{2} \varepsilon^{2}\left\|V^{(2)}\right\|_{\ell \infty}\right)\left\|U^{(2)}\right\|_{\ell^{2}}^{2} \\
& +\left(c_{1}^{2}-\alpha_{2} \varepsilon^{2} C_{0}-\alpha_{2} \varepsilon^{2}\left\|U^{(1)}\right\|_{\ell \infty}\right)\left\|V^{(1)}\right\|_{\ell^{2}}^{2} \\
& +\left(c_{2}^{2}-\alpha_{2} \varepsilon^{2} C_{0}-\frac{2}{3} \alpha_{1} \varepsilon^{2}\left\|V^{(2)}\right\|_{\ell \infty}\right)\left\|V^{(2)}\right\|_{\ell^{2}}^{2}
\end{aligned}
$$

For fixed $c_{1}, c_{2}>0$, we use the bound $\|U\|_{\ell \infty} \leq\|U\|_{\ell^{2}}$ and choose $\varepsilon_{0}>0$ and $K_{0}>0$ such that

$$
\begin{aligned}
& c_{1}^{2}-2 \alpha_{1} \varepsilon_{0}^{2} C_{0}-\frac{2}{3} \alpha_{1} \varepsilon_{0}^{2}\left(2 K_{0} E_{0}\right)^{1 / 2} \geq \min \left(1, K_{0}^{-1}\right) \\
& c_{2}^{2}-\alpha_{2} \varepsilon_{0}^{2} C_{0}-\alpha_{2} \varepsilon_{0}^{2}\left(2 K_{0} E_{0}\right)^{1 / 2} \geq \min \left(1, K_{0}^{-1}\right) \\
& c_{1}^{2}-\alpha_{2} \varepsilon_{0}^{2} C_{0}-\alpha_{2} \varepsilon_{0}^{2}\left(2 K_{0} E_{0}\right)^{1 / 2} \geq \min \left(1, K_{0}^{-1}\right) \\
& c_{2}^{2}-\alpha_{2} \varepsilon_{0}^{2} C_{0}-\frac{2}{3} \alpha_{1} \varepsilon_{0}^{2}\left(2 K_{0} E_{0}\right)^{1 / 2} \geq \min \left(1, K_{0}^{-1}\right)
\end{aligned}
$$

which is always possible if $\varepsilon_{0}$ is sufficiently small. This gives the bound (4.17) with $K_{0}$ redefined as $\max \left(1, K_{0}\right)$.

The following lemma uses the coercivity of the energy $E(t)$ in Lemma 4 to establish the rate at which it may grow in time along the solutions of system (4.12), (4.13), and (4.14). We will be able to use this in Step 4, along with a Gronwall lemma argument of Lemma 6 below, in order to get a bound on the size of the energy quantity. This will in turn gives a bound on how far solutions of the KP-II equation (2.9) drift away from solutions of the FPU system (4.1) and hence will complete the proof of Theorem 1.

Lemma 5. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\left(\mathbb{R}^{2}\right)\right)$ be a solution to the KP-II equation (2.9) with $s \geq 0$ in the class of functions of Lemma 1 and assume that $E(t) \leq E_{0}$ for some $\varepsilon$-independent constant $E_{0}>0$ for every $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$. There exist some constants $\varepsilon_{0}>0$ and $K_{0}>0$ that depend on $A$ such that

$$
\begin{equation*}
\left|E^{\prime}(t)\right| \leq K_{0}\left(\varepsilon^{\frac{7}{2}} E(t)^{\frac{1}{2}}+\varepsilon^{3} E(t)\right) \tag{4.18}
\end{equation*}
$$

for each $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Proof. By differentiating $E(t)$, defined by (4.16), in time $t$, we obtain

$$
\begin{aligned}
E^{\prime}(t)= & \sum_{j, k \in \mathbb{Z}^{2}} \dot{W}_{j, k} W_{j, k}+\dot{Z}_{j, k} Z_{j, k}+c_{1}^{2} \dot{U}_{j, k}^{(1)} U_{j, k}^{(1)}+c_{2}^{2} \dot{U}_{j, k}^{(2)} U_{j, k}^{(2)}+c_{1}^{2} \dot{V}_{j, k}^{(1)} V_{j, k}^{(1)}+c_{2}^{2} \dot{V}_{j, k}^{(2)} V_{j, k}^{(2)} \\
& +\alpha_{1} \varepsilon^{2}\left[\dot{A}\left(U_{j, k}^{(1)}\right)^{2}+2 A \dot{U}_{j, k}^{(1)} U_{j, k}^{(1)}+\dot{U}_{j, k}^{(1)}\left(U_{j, k}^{(1)}\right)^{2}+\dot{V}_{j, k}^{(2)}\left(V_{j, k}^{(2)}\right)^{2}\right] \\
& +\alpha_{2} \varepsilon^{2}\left[\dot{B}_{\varepsilon} U_{j, k}^{(2)} V_{j, k}^{(2)}+\frac{1}{2} \dot{U}_{j, k}^{(1)}\left(V_{j, k}^{(1)}\right)^{2}+U_{j, k}^{(1)} \dot{V}_{j, k}^{(1)} V_{j, k}^{(1)}+\frac{1}{2}\left(U_{j, k}^{(2)}\right)^{2} \dot{V}_{j, k}^{(2)}\right. \\
& \left.+\dot{U}_{j, k}^{(2)} U_{j, k}^{(2)} V_{j, k}^{(2)}+B_{\varepsilon} \dot{U}_{j, k}^{(2)} V_{j, k}^{(2)}+B_{\varepsilon} U_{j, k}^{(2)} \dot{V}_{j, k}^{(2)}+\frac{1}{2} \dot{A}\left(V_{j, k}^{(1)}\right)^{2}+A \dot{V}_{j, k}^{(1)} V_{j, k}^{(1)}\right]
\end{aligned}
$$

where the dot denotes derivative in $t$ and is applied with the chain rule to $A$ and $U_{\varepsilon}$ that depends on $\left(\varepsilon\left(j-c_{1} t\right), \varepsilon^{2} k, \varepsilon^{3} t\right)$. Substituting equations of motion (4.12), (4.13), and (4.14) and summing across $(j, k) \in \mathbb{Z}^{2}$ simplifies $E^{\prime}(t)$ to the form:

$$
\begin{aligned}
E^{\prime}(t)= & \sum_{j, k \in \mathbb{Z}^{2}} W_{j, k} \operatorname{Res}_{j, k}^{W}+Z_{j, k} \operatorname{Res}_{j, k}^{Z} \\
& +\left(c_{1}^{2} U_{j, k}^{(1)}+2 \alpha_{1} \varepsilon^{2} A U_{j, k}^{(1)}+\alpha_{1} \varepsilon^{2}\left(U_{j, k}^{(1)}\right)^{2}+\frac{1}{2} \alpha_{2} \varepsilon^{2}\left(V_{j, k}^{(1)}\right)^{2}\right) R e s U^{(1)} \\
& +\left(c_{2}^{2} U_{j, k}^{(2)}+\alpha_{2} \varepsilon^{2} B_{\varepsilon} V_{j, k}^{(2)}+\alpha_{2} \varepsilon^{2} U_{j, k}^{(2)} V_{j, k}^{(2)}\right) \operatorname{Res}^{U^{(2)}} \\
& +\alpha_{1} \varepsilon^{2}\left(-c_{1} \varepsilon \partial_{\xi} A+\varepsilon^{3} \partial_{\tau} A\right)\left(U_{j, k}^{(1)}\right)^{2} \\
& +\alpha_{2} \varepsilon^{2}\left(-c_{1} \varepsilon \partial_{\xi} B_{\varepsilon}+\varepsilon^{3} \partial_{\tau} B_{\varepsilon}\right) U_{j, k}^{(2)} V_{j, k}^{(2)} \\
& +\frac{\alpha_{2}}{2} \varepsilon^{2}\left(-c_{1} \varepsilon \partial_{\xi} A+\varepsilon^{3} \partial_{\tau} A\right)\left(V_{j, k}^{(1)}\right)^{2}
\end{aligned}
$$

Applying the Cauchy-Schwartz inequality and the bound $\|U\|_{\ell^{\infty}} \leq\|U\|_{\ell^{2}}$ yields

$$
\begin{aligned}
\left|E^{\prime}(t)\right| \leq & \|W\|_{\ell^{2}}\left\|R e s^{W}\right\|_{\ell^{2}}+\|Z\|_{\ell^{2}}\left\|R^{2} s^{Z}\right\|_{\ell^{2}} \\
& +\left(c_{1}^{2}\left\|U^{(1)}\right\|_{\ell^{2}}+2 \alpha_{1} \varepsilon^{2}\|A\|_{L^{\infty}}\left\|U^{(1)}\right\|_{\ell^{2}}+\alpha_{1} \varepsilon^{2}\left\|U^{(1)}\right\|_{\ell^{2}}^{2}+\frac{1}{2} \alpha_{2} \varepsilon^{2}\left\|V^{(1)}\right\|_{\ell^{2}}^{2}\right)\left\|R e s^{U^{(1)}}\right\|_{\ell^{2}} \\
& +\left(c_{2}^{2}\left\|U^{(2)}\right\|_{\ell^{2}}+\alpha_{2} \varepsilon^{2}\left\|B_{\varepsilon}\right\|_{L^{\infty}}\left\|V^{(2)}\right\|_{\ell^{2}}+\alpha_{2} \varepsilon^{2}\left\|U^{(2)}\right\|_{\ell^{2}}\left\|V^{(2)}\right\|_{\ell^{2}}\right)\left\|R e s^{U^{(2)}}\right\|_{\ell^{2}} \\
& +\varepsilon^{2}\left(c_{1} \varepsilon\left\|\partial_{\xi} A\right\|_{L^{\infty}}+\varepsilon^{3}\left\|\partial_{\tau} A\right\|_{L^{\infty}}\right)\left(\alpha_{1}\left\|U^{(1)}\right\|_{\ell^{2}}^{2}+\frac{1}{2} \alpha_{2}\left\|V^{(1)}\right\|_{\ell^{2}}^{2}\right) \\
& +\varepsilon^{2}\left(c_{1} \varepsilon\left\|\partial_{\xi} B_{\varepsilon}\right\|_{L^{\infty}}+\varepsilon^{3}\left\|\partial_{\tau} B_{\varepsilon}\right\|_{L^{\infty}}\right)\left\|U^{(2)}\right\|_{\ell^{2}}\left\|V^{(2)}\right\|_{\ell^{2}}
\end{aligned}
$$

Estimating the residual terms and the perturbation terms with the help of Lemmas 3 and 4, respectively, yields (4.18).

### 4.4. Step 4. Bound on the approximation error

By making the substitution $E(t):=\frac{1}{2} Q(t)^{2}$, we obtain from (4.18):

$$
\begin{equation*}
\left|Q^{\prime}(t)\right| \leq K_{0}\left(\varepsilon^{\frac{7}{2}}+\varepsilon^{3} Q\right) \tag{4.19}
\end{equation*}
$$

where the constant $K_{0}$ may change from one line to another line. The norm of the perturbation terms controlled by $Q(t)$ is further estimated by using the Gronwall's inequality.
Lemma 6. Assume that $Q(t)$ satisfies (4.19) for $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$ and $Q(0) \leq C_{0} \varepsilon^{\frac{1}{2}}$ for some $\varepsilon$ independent constant $C_{0}$. There exists $\varepsilon_{0}>0$ such that

$$
\begin{equation*}
Q(t) \leq \varepsilon^{\frac{1}{2}}\left(1+C_{0}\right) \exp \left(K_{0} \tau_{0}\right) \tag{4.20}
\end{equation*}
$$

for each $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Proof. By using the integrating factor, we can rewrite (4.19) in the form:

$$
\begin{equation*}
\frac{d}{d t}\left[\exp \left(-\varepsilon^{3} K_{0} t\right) Q\right] \leq K_{0} \varepsilon^{\frac{7}{2}} \exp \left(-\varepsilon^{3} K_{0} t\right) \tag{4.21}
\end{equation*}
$$

Integrating (4.21) yields the Gronwall's inequality

$$
\begin{equation*}
Q(t) \leq\left(Q(0)+\varepsilon^{\frac{1}{2}}\right) \exp \left(\varepsilon^{3} K_{0} t\right) \tag{4.22}
\end{equation*}
$$

Since $Q(0) \leq C \varepsilon^{\frac{1}{2}}$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$, the inequality (4.22) yields (4.20).
We can finish the proof of Theorem 1 by using Lemmas 4 and 6 . Since

$$
Q(0) \leq C_{A}\left(\left\|U_{i n}^{(1)}\right\|_{\ell^{2}}+\left\|U_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|W_{i n}\right\|_{\ell^{2}}+\left\|V_{i n}^{(1)}\right\|_{\ell^{2}}+\left\|V_{i n}^{(2)}\right\|_{\ell^{2}}+\left\|Z_{i n}\right\|_{\ell^{2}}\right),
$$

where the subscript in stands for the initial condition, the decomposition (4.2) and the hypothesis (2.10) yield that $Q(0) \leq C \varepsilon^{\frac{1}{2}}$, so that Lemma 6 gives the bound (4.20). With decomposition (4.2) and Lemma 4 , we have that

$$
\begin{aligned}
& \left\|u^{(1)}(t)-\varepsilon^{2} A\left(\varepsilon\left(j-c_{1} t\right), \eta^{2} k, \varepsilon^{3} t\right)\right\|_{\ell^{2}}^{2}+\left\|u^{(2)}(t)-\varepsilon^{2} B_{\varepsilon}\left(\varepsilon\left(j-c_{1} t\right), \eta^{2} k, \varepsilon^{3} t\right)\right\|_{\ell^{2}}^{2} \\
& +\left\|w(t)-\varepsilon^{2} W_{\varepsilon}\left(\varepsilon\left(j-c_{1} t\right), \eta^{2} k, \varepsilon^{3} t\right)\right\|_{\ell^{2}}^{2}+\left\|v^{(1)}(t)\right\|_{\ell^{2}}^{2}+\left\|v^{(2)}(t)\right\|_{\ell^{2}}^{2}+\|z(t)\|_{\ell^{2}}^{2} \leq K_{0} \varepsilon^{4} Q(t)^{2},
\end{aligned}
$$

where the $\varepsilon$-dependent functions $W_{\varepsilon}$ and $B_{\varepsilon}$ are given in terms of $A$ by (4.7) and (4.11), respectively. Due to the bound (4.20) and the triangle inequality, we obtain the bound (2.11) and the result of Theorem 1 follows.

## 5. Proof of Theorem 2

Here, we give relevant details of the proof of Theorem 2. As is explained in the introduction, we will only consider the reduction of the general FPU system if $c_{1}=c_{2}$ and $\alpha_{2}=2 \alpha_{1}$, when the vertical and horizontal displacements on the square two-dimensional lattice coincide with $x_{j, k}=y_{j, k}$.

Instead of working with the strain variables in (2.14), we introduce the following strain variables (see Fig. 2):

$$
\left\{\begin{array}{l}
a_{m, n}^{l}=\chi_{m, n}-x_{m, n},  \tag{5.1}\\
a_{m, n}^{d}=x_{m+1, n+1}-\chi_{m, n}, \\
a_{m, n}^{x}=x_{m+1, n}-\chi_{m, n} \\
a_{m, n}^{y}=x_{m, n+1}-\chi_{m, n}
\end{array}\right.
$$

in order to write equations of motion in the form:

$$
\begin{align*}
\dot{a}_{m, n}^{l}= & v_{m, n}-u_{m, n}, \\
\dot{a}_{m, n}^{d}= & u_{m+1, n+1}-v_{m, n}, \\
\dot{a}_{m, n}^{x}= & u_{m+1, n}-v_{m, n}, \\
\dot{a}_{m, n}^{y}= & u_{m, n+1}-v_{m, n} \\
\dot{u}_{m, n}= & c_{1}^{2}\left(a_{m, n}^{l}-a_{m-1, n-1}^{d}-a_{m-1, n}^{x}-a_{m, n-1}^{y}\right)  \tag{5.2}\\
& +2 \alpha_{1}\left[\left(a_{m, n}^{l}\right)^{2}-\left(a_{m-1, n-1}^{d}\right)^{2}-\left(a_{m-1, n}^{x}\right)^{2}+\left(a_{m, n-1}^{y}\right)^{2}\right], \\
\dot{v}_{m, n}= & c_{1}^{2}\left(a_{m, n}^{d}-a_{m, n}^{l}+a_{m, n}^{x}+a_{m, n}^{y}\right) \\
& +2 \alpha_{1}\left[\left(a_{m, n}^{d}\right)^{2}-\left(a_{m, n}^{l}\right)^{2}+\left(a_{m, n}^{x}\right)^{2}-\left(a_{m, n}^{y}\right)^{2}\right],
\end{align*}
$$

where $u_{m, n}:=\dot{x}_{m, n}, v_{m, n}:=\dot{\chi}_{m, n}$, and $(m, n) \in \mathbb{Z}^{2}$. The justification procedure is divided into the same four steps as in the case of the horizontal propagation.

### 5.1. Step 1. Decomposition

We will use the following decomposition,

$$
\begin{align*}
a_{m, n}^{l} & =\varepsilon^{2} L_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} L_{m, n}, \\
a_{m, n}^{d} & =\varepsilon^{2} D_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} D_{m, n}, \\
a_{m, n}^{x} & =\varepsilon^{2} X_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} X_{m, n},  \tag{5.3}\\
a_{m, n}^{y} & =\varepsilon^{2} Y_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} Y_{m, n}, \\
u_{m, n} & =\varepsilon^{2} U_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} U_{m, n}, \\
v_{m, n} & =\varepsilon^{2} V_{\varepsilon}(\xi, \eta, \tau)+\varepsilon^{2} V_{m, n},
\end{align*}
$$

where $\xi=\varepsilon\left(m-c_{1}^{*} t\right), \eta=\varepsilon^{2} n$, and $\tau=\varepsilon^{3} t$ with $c_{1}^{*}:=\frac{c_{1}}{\sqrt{2}}$. By ignoring the error terms and the residual terms of the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ for the time being, we shall use the equations of motion (5.2) and define the expansions of the functions $L_{\varepsilon}, \ldots, V_{\varepsilon}$ in $\varepsilon$ from the condition that all residual terms of the formal order below $\mathcal{O}\left(\varepsilon^{5}\right)$ are removed.

The first equation in system (5.2) gives us the relationship:

$$
\begin{equation*}
-\varepsilon c_{1}^{*} \partial_{\xi} L_{\varepsilon}+\varepsilon^{3} \partial_{\tau} L_{\varepsilon}=V_{\varepsilon}-U_{\varepsilon} \tag{5.4}
\end{equation*}
$$

which is used to eliminate $V_{\varepsilon}$ from all other relations.

Adding the first and third equations in system (5.2) implies

$$
\begin{equation*}
-\varepsilon c_{1}^{*} \partial_{\xi}\left(L_{\varepsilon}+X_{\varepsilon}\right)+\varepsilon^{3} \partial_{\tau}\left(L_{\varepsilon}+X_{\varepsilon}\right)=U_{\varepsilon}(\xi+\varepsilon, \eta)-U_{\varepsilon}(\xi, \eta), \tag{5.5}
\end{equation*}
$$

which coincides with equation (4.3) up to notations. As follows from (2.12), we set

$$
\begin{equation*}
X_{\varepsilon}+L_{\varepsilon}=A \tag{5.6}
\end{equation*}
$$

where $A$ is a suitable solution of the KP-II equation (2.13). Since (5.5) coincides with (4.3), we rewrite expansions (4.5) and (4.7) in new notations:

$$
\begin{equation*}
U_{\varepsilon}=-c_{1}^{*} A+\varepsilon\left(\frac{c_{1}^{*}}{2} \partial_{\xi} A\right)+\varepsilon^{2}\left(\partial_{\xi}^{-1} \partial_{\tau} A-\frac{c_{1}^{*}}{12} \partial_{\xi}^{2} A\right)-\varepsilon^{3}\left(\frac{1}{2} \partial_{\tau} A\right) . \tag{5.7}
\end{equation*}
$$

Adding the first and fourth equations in system (5.2) implies

$$
\begin{equation*}
-\varepsilon c_{1}^{*} \partial_{\xi}\left(L_{\varepsilon}+Y_{\varepsilon}\right)+\varepsilon^{3} \partial_{\tau}\left(L_{\varepsilon}+Y_{\varepsilon}\right)=U_{\varepsilon}\left(\xi, \eta+\varepsilon^{2}\right)-U_{\varepsilon}(\xi, \eta) \tag{5.8}
\end{equation*}
$$

which coincides with Eq. (4.4) up to notations, Again, we rewrite expansions (4.8) and (4.11) in new notations:

$$
\begin{equation*}
Y_{\varepsilon}+L_{\varepsilon}=\varepsilon \partial_{\xi}^{-1} \partial_{\eta} A-\varepsilon^{2}\left(\frac{1}{2} \partial_{\eta} A\right)+\varepsilon^{3}\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{12} \partial_{\eta} \partial_{\xi} A\right) . \tag{5.9}
\end{equation*}
$$

Finally, adding the first and second equations in system (5.2) implies

$$
\begin{equation*}
-\varepsilon c_{1}^{*} \partial_{\xi}\left(L_{\varepsilon}+D_{\varepsilon}\right)+\varepsilon^{3} \partial_{\tau}\left(L_{\varepsilon}+D_{\varepsilon}\right)=U_{\varepsilon}\left(\xi+\varepsilon, \eta+\varepsilon^{2}\right)-U_{\varepsilon}(\xi, \eta) \tag{5.10}
\end{equation*}
$$

We derive by using Taylor series and expansion (5.7) up to the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ :

$$
\begin{aligned}
U_{\varepsilon}\left(\xi+\varepsilon, \eta+\varepsilon^{2}\right)-U_{\varepsilon}(\xi, \eta)= & \varepsilon \partial_{\xi} U_{\varepsilon}+\varepsilon^{2}\left(\frac{1}{2} \partial_{\xi}^{2} U_{\varepsilon}+\partial_{\eta} U_{\varepsilon}\right) \\
& +\varepsilon^{3}\left(\frac{1}{6} \partial_{\xi}^{3} U_{\varepsilon}+\partial_{\xi} \partial_{\eta} U_{\varepsilon}\right)+\varepsilon^{4}\left(\frac{1}{24} \partial_{\xi}^{4} U_{\varepsilon}+\frac{1}{2} \partial_{\xi}^{2} \partial_{\eta} U_{\varepsilon}+\frac{1}{2} \partial_{\eta}^{2} U_{\varepsilon}\right) \\
= & -c_{1}^{*} \varepsilon \partial_{\xi} A-c_{1}^{*} \varepsilon^{2} \partial_{\eta} A+\varepsilon^{3}\left(\partial_{\tau} A-\frac{c_{1}^{*}}{2} \partial_{\xi} \partial_{\eta} A\right) \\
& +\varepsilon^{4}\left(\partial_{\xi}^{-1} \partial_{\eta} \partial_{\tau} A-\frac{c_{1}^{*}}{12} \partial_{\xi}^{2} \partial_{\eta} A-\frac{c_{1}^{*}}{2} \partial_{\eta}^{2} A\right) .
\end{aligned}
$$

Expanding the left-hand side of equation (5.10) in orders of $\varepsilon$ and comparing with the previous expansions yields

$$
\begin{equation*}
D_{\varepsilon}+L_{\varepsilon}=A+\varepsilon \partial_{\xi}^{-1} \partial_{\eta} A+\varepsilon^{2}\left(\frac{1}{2} \partial_{\eta} A\right)+\varepsilon^{3}\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{12} \partial_{\xi} \partial_{\eta} A\right) . \tag{5.11}
\end{equation*}
$$

All quantities of the decomposition (5.3) are now defined in terms of $A$ and $L_{\varepsilon}$. We can now use the fifth and sixth equations in system (5.2) in order to define $L_{\varepsilon}$ and to verify the validity of the KP-II equation (2.13) for $A$ up to truncation at the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$. The fifth and sixth equations in system (5.2) yield

$$
\begin{align*}
& -\varepsilon c_{1}^{*} \partial_{\xi} U_{\varepsilon}+\varepsilon^{3} \partial_{\tau} U_{\varepsilon}=c_{1}^{2}\left(L_{\varepsilon}(\xi, \eta)-D_{\varepsilon}\left(\xi-\varepsilon, \eta-\varepsilon^{2}\right)-X_{\varepsilon}(\xi-\varepsilon, \eta)-Y_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right)\right) \\
& +2 \alpha_{1} \varepsilon^{2}\left[L_{\varepsilon}(\xi, \eta)^{2}-D_{\varepsilon}\left(\xi-\varepsilon, \eta-\varepsilon^{2}\right)^{2}-X_{\varepsilon}(\xi-\varepsilon, \eta)^{2}+Y_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right)^{2}\right] \tag{5.12}
\end{align*}
$$

and

$$
\begin{align*}
& -\varepsilon c_{1}^{*} \partial_{\xi} V_{\varepsilon}+\varepsilon^{3} \partial_{\tau} V_{\varepsilon}=c_{1}^{2}\left(D_{\varepsilon}(\xi, \eta)-L_{\varepsilon}(\xi, \eta)+X_{\varepsilon}(\xi, \eta)+Y_{\varepsilon}(\xi, \eta)\right) \\
& +2 \alpha_{1} \varepsilon^{2}\left[D_{\varepsilon}(\xi, \eta)^{2}-L_{\varepsilon}(\xi, \eta)^{2}+X_{\varepsilon}(\xi, \eta)^{2}-Y_{\varepsilon}(\xi, \eta)^{2}\right] \tag{5.13}
\end{align*}
$$

In view of equation (5.4), the left-hand side of equation (5.13) is expanded as

$$
-\varepsilon c_{1}^{*} \partial_{\xi} V_{\varepsilon}+\varepsilon^{3} \partial_{\tau} V_{\varepsilon}=-\varepsilon c_{1}^{*} \partial_{\xi} U_{\varepsilon}+\varepsilon^{2}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{2} L_{\varepsilon}+\varepsilon^{3} \partial_{\tau} U_{\varepsilon}-2 \varepsilon^{4} c_{1}^{*} \partial_{\xi} \partial_{\tau} L_{\varepsilon}+\varepsilon^{6} \partial_{\tau}^{2} L_{\varepsilon},
$$

whereas the right-hand side of Eq. (5.13) can be written as

$$
\begin{aligned}
& c_{1}^{2}\left(D_{\varepsilon}+L_{\varepsilon}+X_{\varepsilon}+L_{\varepsilon}+Y_{\varepsilon}+L_{\varepsilon}-4 L_{\varepsilon}\right) \\
& +2 \alpha_{1} \varepsilon^{2}\left[\left(D_{\varepsilon}+L_{\varepsilon}\right)^{2}+\left(X_{\varepsilon}+L_{\varepsilon}\right)^{2}-\left(Y_{\varepsilon}+L_{\varepsilon}\right)^{2}-2 L_{\varepsilon}\left(D_{\varepsilon}+L_{\varepsilon}+X_{\varepsilon}+L_{\varepsilon}-Y_{\varepsilon}-L_{\varepsilon}\right)\right]
\end{aligned}
$$

We expand $L_{\varepsilon}$ in powers of $\varepsilon$ as

$$
\begin{equation*}
L_{\varepsilon}=L^{(0)}+\varepsilon L^{(1)}+\varepsilon^{2} L^{(2)}+\varepsilon^{3} L^{(3)}, \tag{5.14}
\end{equation*}
$$

where the functions $L^{(j)}$ depend on $(\xi, \eta)$ and decay to zero at infinity. Substituting (5.6), (5.7), (5.9), (5.11), and (5.14) into the left-hand and right-hand sides of Eq. (5.13) yields the following equations in different powers of $\varepsilon$ with their corresponding solutions:

$$
\begin{aligned}
\mathcal{O}(1): & 0=2\left(c_{1}^{*}\right)^{2}\left(2 A-4 L^{(0)}\right) \\
& \Longrightarrow L^{(0)}=\frac{1}{2} A \\
\mathcal{O}(\varepsilon): & \left(c_{1}^{*}\right)^{2} \partial_{\xi} A=2\left(c_{1}^{*}\right)^{2}\left(2 \partial_{\xi}^{-1} \partial_{\eta} A-4 L^{(1)}\right) \\
& \Longrightarrow L^{(1)}=\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta} A-\frac{1}{8} \partial_{\xi} A \\
\mathcal{O}\left(\varepsilon^{2}\right): & 0=2\left(c_{1}^{*}\right)^{2}\left(-4 L^{(2)}\right) \\
& \Longrightarrow L^{(2)}=0 \\
\mathcal{O}\left(\varepsilon^{3}\right): & -2 c_{1}^{*} \partial_{\tau} A-\frac{\left(c_{1}^{*}\right)^{2}}{24} \partial_{\xi}^{3} A+\frac{\left(c_{1}^{*}\right)^{2}}{2} \partial_{\xi} \partial_{\eta} A=2\left(c_{1}^{*}\right)^{2}\left(\partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{6} \partial_{\xi} \partial_{\eta} A-4 L^{(3)}\right)+\alpha_{1} A \partial_{\xi} A .
\end{aligned}
$$

By using the KPII equation (2.13), we eliminate

$$
2 c_{1}^{*} \partial_{\tau} A+\alpha_{1} A \partial_{\xi} A=-\frac{1}{48}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{3} A-\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A
$$

and obtain from the equation at the order of $\mathcal{O}\left(\varepsilon^{3}\right)$ that

$$
L^{(3)}=\frac{1}{8} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{384} \partial_{\xi}^{3} A-\frac{1}{48} \partial_{\xi} \partial_{\eta} A .
$$

Substituting this expansion into (5.14) yields the expansion

$$
\begin{equation*}
L_{\varepsilon}=\frac{1}{2} A+\varepsilon\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta} A-\frac{1}{8} \partial_{\xi} A\right)+\varepsilon^{3}\left(\frac{1}{8} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{384} \partial_{\xi}^{3} A-\frac{1}{48} \partial_{\xi} \partial_{\eta} A\right) \tag{5.15}
\end{equation*}
$$

By using (5.6), (5.9), and (5.11), we also obtain

$$
\begin{align*}
X_{\varepsilon}= & \frac{1}{2} A-\varepsilon\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta} A-\frac{1}{8} \partial_{\xi} A\right)-\varepsilon^{3}\left(\frac{1}{8} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\frac{1}{384} \partial_{\xi}^{3} A-\frac{1}{48} \partial_{\xi} \partial_{\eta} A\right),  \tag{5.16}\\
Y_{\varepsilon}= & -\frac{1}{2} A+\varepsilon\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta} A+\frac{1}{8} \partial_{\xi} A\right)-\varepsilon^{2}\left(\frac{1}{2} \partial_{\eta} A\right) \\
& +\varepsilon^{3}\left(\frac{3}{8} \partial_{\xi}^{-1} \partial_{\eta}^{2} A-\frac{1}{384} \partial_{\xi}^{3} A+\frac{5}{48} \partial_{\xi} \partial_{\eta} A\right),  \tag{5.17}\\
D_{\varepsilon}= & \frac{1}{2} A+\varepsilon\left(\frac{1}{2} \partial_{\xi}^{-1} \partial_{\eta} A+\frac{1}{8} \partial_{\xi} A\right)+\varepsilon^{2}\left(\frac{1}{2} \partial_{\eta} A\right) \\
& +\varepsilon^{3}\left(\frac{3}{8} \partial_{\xi}^{-1} \partial_{\eta}^{2} A-\frac{1}{384} \partial_{\xi}^{3} A+\frac{5}{48} \partial_{\xi} \partial_{\eta} A\right), \tag{5.18}
\end{align*}
$$

Finally, substituting decompositions (5.7), (5.15), (5.16), (5.17), and (5.18) into (5.12) gives the expansion:

$$
\varepsilon\left(c_{1}^{*}\right)^{2} \partial_{\xi} A-\frac{1}{2} \varepsilon^{2}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{2} A+\varepsilon^{3}\left(-2 c_{1}^{*} \partial_{\tau} A+\frac{1}{12}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{3} A\right)+\varepsilon^{4} c_{1}^{*} \partial_{\xi} \partial_{\tau} A
$$

$$
\begin{aligned}
&=\varepsilon\left(c_{1}^{*}\right)^{2} \partial_{\xi} A-\frac{1}{2} \varepsilon^{2}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{2} A+\varepsilon^{3}\left(\frac{5}{48}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{3} A+\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{-1} \partial_{\eta}^{2} A+\alpha_{1} A \partial_{\xi} A\right) \\
&+\varepsilon^{4}\left(-\frac{1}{96}\left(c_{1}^{*}\right)^{2} \partial_{\xi}^{4} A-\frac{1}{2}\left(c_{1}^{*}\right)^{2} \partial_{\eta}^{2} A-\frac{1}{2} \alpha_{1} \partial_{\xi}\left(A \partial_{\xi} A\right)\right),
\end{aligned}
$$

which is satisfied up to the formal order of $\mathcal{O}\left(\varepsilon^{5}\right)$ if $A$ is a suitable solution of the KP-II equation (2.13).

### 5.2. Step 2. Residual terms

Plugging the decomposition (5.3) into equations of motion (5.2) gives the following equations for the error terms:

$$
\begin{align*}
\dot{L}_{m, n}= & V_{m, n}-U_{m, n}, \\
\dot{D}_{m, n}= & U_{m+1, n+1}-V_{m, n}+\operatorname{Res}_{m, n}^{D}, \\
\dot{X}_{m, n}= & U_{m+1, n}-V_{m, n}+\operatorname{Res}_{m, n}^{X}, \\
\dot{Y}_{m, n}= & U_{m, n+1}-V_{m, n}+\operatorname{Res}_{m, n}^{Y}, \\
\dot{U}_{m, n}= & c_{1}^{2}\left(L_{m, n}-D_{m-1, n-1}-X_{m-1, n}-Y_{m, n-1}\right) \\
& +2 \alpha_{1} \varepsilon^{2}\left[L_{m, n}^{2}-D_{m-1, n-1}^{2}-X_{m-1, n}^{2}+Y_{m, n-1}^{2}\right] \\
& +4 \alpha_{1} \varepsilon^{2}\left[L_{m, n} L_{\varepsilon}(\xi, \eta)-D_{m-1, n-1} D_{\varepsilon}\left(\xi-\varepsilon, \eta-\varepsilon^{2}\right)\right]  \tag{5.19}\\
& +4 \alpha_{1} \varepsilon^{2}\left[Y_{m, n-1} Y_{\varepsilon}\left(\xi, \eta-\varepsilon^{2}\right)-X_{m-1, n} X_{\varepsilon}(\xi-\varepsilon, \eta)\right] \\
& +\operatorname{Res}_{m, n}^{U}, \\
\dot{V}_{m, n}=c_{1}^{2} & \left(D_{m, n}-L_{m, n}+X_{m, n}+Y_{m, n}\right) \\
& +2 \alpha_{1} \varepsilon^{2}\left[D_{m, n}^{2}-L_{m, n}^{2}+X_{m, n}^{2}-Y_{m, n}^{2}\right] \\
& +4 \alpha_{1} \varepsilon^{2}\left[D_{m, n} D_{\varepsilon}-L_{m, n} L_{\varepsilon}+X_{m, n} X_{\varepsilon}-Y_{m, n} Y_{\varepsilon}\right]+\operatorname{Res}_{m, n}^{V},
\end{align*}
$$

where

$$
\begin{aligned}
\operatorname{Res}_{m, n}^{D} & :=U_{\varepsilon}\left(\xi+\varepsilon, \eta+\varepsilon^{2}\right)-V_{\varepsilon}(\xi, \eta)+\varepsilon c_{1}^{*} \partial_{\xi} D_{\varepsilon}-\varepsilon^{3} \partial_{\tau} D_{\varepsilon}, \\
\operatorname{Res}_{m, n}^{X} & :=U_{\varepsilon}(\xi+\varepsilon, \eta)-V_{\varepsilon}(\xi, \eta)+\varepsilon c_{1}^{*} \partial_{\xi} X_{\varepsilon}-\varepsilon^{3} \partial_{\tau} X_{\varepsilon}, \\
\operatorname{Res}_{m, n}^{Y} & :=U_{\varepsilon}\left(\xi, \eta+\varepsilon^{2}\right)-V_{\varepsilon}(\xi, \eta)+\varepsilon c_{1}^{*} \partial_{\xi} Y_{\varepsilon}-\varepsilon^{3} \partial_{\tau} Y_{\varepsilon},
\end{aligned}
$$

and the residuals $\operatorname{Res}^{U}$ and $\operatorname{Res}^{V}$ are computed from the residual terms of equations (5.12) and (5.13). Similarly to Lemma 3, the residual terms are controlled in the $\ell^{2}\left(\mathbb{Z}^{2}\right)$ norm if $A$ is a smooth solution of the KP-II equation (2.13). This estimate is summarized in the following lemma, which we give without proof.

Lemma 7. Let $A \in C^{0}\left(\mathbb{R}, H^{s}\right)$ be a solution to the KP-II equation (2.13) with $s \geq 9$. There is a positive constant $C$ that depend on $A$ such that for all $\varepsilon \in(0,1]$, we have

$$
\begin{equation*}
\left\|\operatorname{Res}^{D}\right\|_{\ell^{2}}+\left\|\operatorname{Res}^{X}\right\|_{\ell^{2}}+\left\|\operatorname{Res}^{Y}\right\|_{\ell^{2}}+\left\|\operatorname{Res}^{U}\right\|_{\ell^{2}}+\left\|\operatorname{Res}^{V}\right\|_{\ell^{2}} \leq C \varepsilon^{\frac{7}{2}} . \tag{5.20}
\end{equation*}
$$

### 5.3. Step 3. Energy estimates

In order to control the growth of the approximation error from solutions to system (5.19), we introduce the following energy function,

$$
\begin{align*}
E(t)= & \sum_{m, n} \frac{1}{2}\left(U_{m, n}^{2}+V_{m, n}^{2}\right)+\frac{1}{2} c_{1}^{2}\left(L_{m, n}^{2}+D_{m, n}^{2}+X_{m, n}^{2}+Y_{m, n}^{2}\right) \\
& +\sum_{m, n} 2 \alpha_{1} \varepsilon^{2}\left(L_{m, n}^{2} L_{\varepsilon}+D_{m, n}^{2} D_{\varepsilon}+X_{m, n}^{2} X_{\varepsilon}-Y_{m, n}^{2} Y_{\varepsilon}\right)  \tag{5.21}\\
& +\sum_{m, n} \frac{2}{3} \alpha_{1} \varepsilon^{2}\left(L_{m, n}^{3}+D_{m, n}^{3}+X_{m, n}^{3}-Y_{m, n}^{3}\right) .
\end{align*}
$$

Similarly to the proof of Lemma 4, the energy is coercive with respect to the $\ell^{2}$ norm of the perturbations if $\varepsilon$ is sufficiently small and the perturbations are not large in the $\ell^{2}$ norm. The only difference between the expansions (5.15), (5.16), (5.17), and (5.18) from the expansion (4.11) is that the former involves three derivatives of $A$ and one derivative of $\partial_{\xi}^{-1} \partial_{\eta} A$, whereas the latter involves two derivatives of $A$ and one derivative of $\partial_{\xi}^{-1} \partial_{\eta} A$. This modifies the statement of the following lemma, which we give without proof.

Lemma 8. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+1}\left(\mathbb{R}^{2}\right)\right)$ and $\partial_{\xi}^{-1} A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s}\left(\mathbb{R}^{2}\right)\right)$ with $s>3$ and assume that $E(t) \leq E_{0}$ for some $\varepsilon$-independent constant $E_{0}>0$ for every $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$. There exists some constants $\varepsilon_{0}>0$ and $K_{0}>0$ that depend on $A$ such that

$$
\begin{equation*}
\|U\|_{\ell^{2}}^{2}+\|V\|_{\ell^{2}}^{2}+\|L\|_{\ell^{2}}^{2}+\|D\|_{\ell^{2}}^{2}+\|X\|_{\ell^{2}}^{2}+\|Y\|_{\ell^{2}}^{2} \leq 2 K_{0} E(t), \tag{5.22}
\end{equation*}
$$

for each $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.
Finally, the growth of the energy (5.21) is estimated from the balance equation:

$$
\begin{align*}
E^{\prime}(t)= & \sum_{m, n} U_{m, n} \operatorname{Res}_{m, n}^{U}+V_{m, n} \operatorname{Res}_{m, n}^{V} \\
& +c_{1}^{2} \sum_{m, n} D_{m, n} \operatorname{Res}_{m, n}^{D}+X_{m, n} \operatorname{Res}_{m, n}^{X}+Y_{m, n} \operatorname{Res}_{m, n}^{Y} \\
& +4 \alpha_{1} \varepsilon^{2} \sum_{m, n} D_{m, n}^{2} \operatorname{Res}_{m, n}^{D}+X_{m, n}^{2} \operatorname{Res}_{m, n}^{X}-Y_{m, n}^{2} \operatorname{Res}_{m, n}^{Y}  \tag{5.23}\\
& +4 \alpha_{1} \varepsilon^{2} \sum_{m, n} D_{m, n} D_{\varepsilon} \operatorname{Res}_{m, n}^{D}+X_{m, n} X_{\varepsilon} \operatorname{Res}_{m, n}^{X}-Y_{m, n} Y_{\varepsilon} \operatorname{Res}_{m, n}^{Y} \\
& +2 \alpha_{1} \varepsilon^{2} \sum_{m, n} L_{m, n}^{2} \dot{L}_{\varepsilon}+D_{m, n}^{2} \dot{D}_{\varepsilon}+X_{m, n}^{2} \dot{X}_{\varepsilon}-Y_{m, n}^{2} \dot{Y}_{\varepsilon},
\end{align*}
$$

where the dot denotes the derivative in $t$ of the function of $\xi=\varepsilon\left(m-c_{1}^{*} t\right), \eta=\varepsilon^{2} n$, and $\tau=\varepsilon^{3} t$. In view of Lemmas 7 and 8 , similar to the proof of Lemma 5 , we can obtain a bound on the growth of the energy. This bound is summarized in the following lemma, which we give without proof.

Lemma 9. Let $A \in C^{0}\left(\left[-\tau_{0}, \tau_{0}\right], H^{s+9}\left(\mathbb{R}^{2}\right)\right)$ be a solution to the KP-II equation (2.13) with $s \geq 0$ in the class of functions of Lemma 1 and assume that $E(t) \leq E_{0}$ for some $\varepsilon$-independent constant $E_{0}>0$ for every $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$. There exist some constants $\varepsilon_{0}>0$ and $K_{0}>0$ that depend on $A$ such that

$$
\begin{equation*}
\left|E^{\prime}(t)\right| \leq K_{0}\left(\varepsilon^{\frac{7}{2}} E(t)^{\frac{1}{2}}+\varepsilon^{3} E(t)\right) \tag{5.24}
\end{equation*}
$$

for each $\varepsilon \in\left(0, \varepsilon_{0}\right)$ and $t \in\left[-\tau_{0} \varepsilon^{-3}, \tau_{0} \varepsilon^{-3}\right]$.

### 5.4. Step 4. Bound on the approximation error

Since the bounds (4.18) and (5.24) coincide, application of the Gronwall's inequality in Lemma 6 gives the desired result of Theorem 2 exactly like in Step 4 of the proof of Theorem 1.

## 6. Conclusion

We have proved here the validity of the KP-II approximation for dynamics of transversely modulated small-amplitude long-scale waves in a vector FPU system on a two-dimensional square lattice. The justification was performed for horizontal and vertical propagations of the waves and, under some restrictions on parameters of the FPU system, for the diagonal propagation. While the general algorithm of the justification analysis is well understood by now, the technical details of the justification analysis have been developed for the first time in the vector FPU systems, to the best of our knowledge.

This research opens up new directions. First, it is interesting to see if the justification analysis can be generalized for the vector FPU mass-spring systems with diagonal springs and for the wave propagation under an arbitrary angle with respect to the square lattice. Second, in terms of applications of the FPU models to the graphene materials, it is important to consider other two-dimensional models such as hexagonal lattices. Finally, known properties of the KP-II equation can be applied to study other problems of the nonlinear dynamics of small-amplitude waves in the two-dimensional FPU lattices such as the linear and nonlinear stability of periodic and solitary waves with respect to transverse modulations.

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